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Ref. No.:  
324-06121454

### **Overview and Technical Data:**

## **STARRAG HECKERT - CWK 400 D with palett changer + aluminium option**

### **STARRAG HECKERT**



# starrag

Starrag Group

Year of Build:  
May 1999

**Description:**

**Used STARRAG HECKERT FCWK 400D Dynamic 6-station pallet pool, 240 Tower magazine with aluminum finish**

- New spindle at 16 116 hours
- About. 33 568 operating hours
- CNC control Siemens 840 D
- Travel:
  - Column longitudinal travel X-axis 650 mm
  - Support vertical travel 650 mm Y-axis
  - Table traverse Z-axis 650 mm
  - B-axis 360 degrees x 0.001 indexing
  - Rapid traverse 40 m / min.
- Pallet size 400 x 400 mm
- Max Belastung 400 kp
- Drilling / tool spindle speed of 50 to max.15.000 r / min
- Drive power 31 KW
- Tool holder HSK 63
- Dynamic range change in 8 to 9 s by hydraulic rotary changer
- Coolant system
- Dimensions approximately 5.4 x 2.87 x 4.23 m

The motor spindles and speeds of 15 000 rev / min are creating the ideal conditions for the light metal processing, without compromising the high static and dynamic stiffness of the cast iron and steel processing.

The CWK 400 D Dynamic reach peak values?: Eilgangwerte to 100 m / min and accelerations up to 15 m/s<sup>2</sup>.

Innovative ideas also stuck in tool handling with the proven tower magazines with 240 tools. Attending dynamics is called for: in 1.5 s is provided the next tool, to 3.5 s to 4 s, the chip-to-chip time is reduced.

Compact in design, space-saving features of the circular memory 6 presets and 1 clamping space. It is powered by an AC servo motor.

For more details see PDFs

## Technical Data:

### Technical Data:

Control:

SINUMERIK 840D

Machine Hours:

33.568 hrs.

Spindle Hours:

16.116 hrs.

Spindle Speed:

15.000 rpm

Tool Capacity:

240 x

## **Travels:**

X-Axis:

650 mm

Y-Axis:

650mm

Z-Axis:

650 mm

## **Dimensions and Weight:**

Height:

2.870 mm

Width:

4.230 mm

Length:

5.400 mm

Weight:

12.800 kg

## **Buyer Information:**

Condition:

Very good condition

Availability:

Sold

Sold as:

EXW (Ex Works - Incoterm)

VAT:

19 %

Location:

Germany



1



2





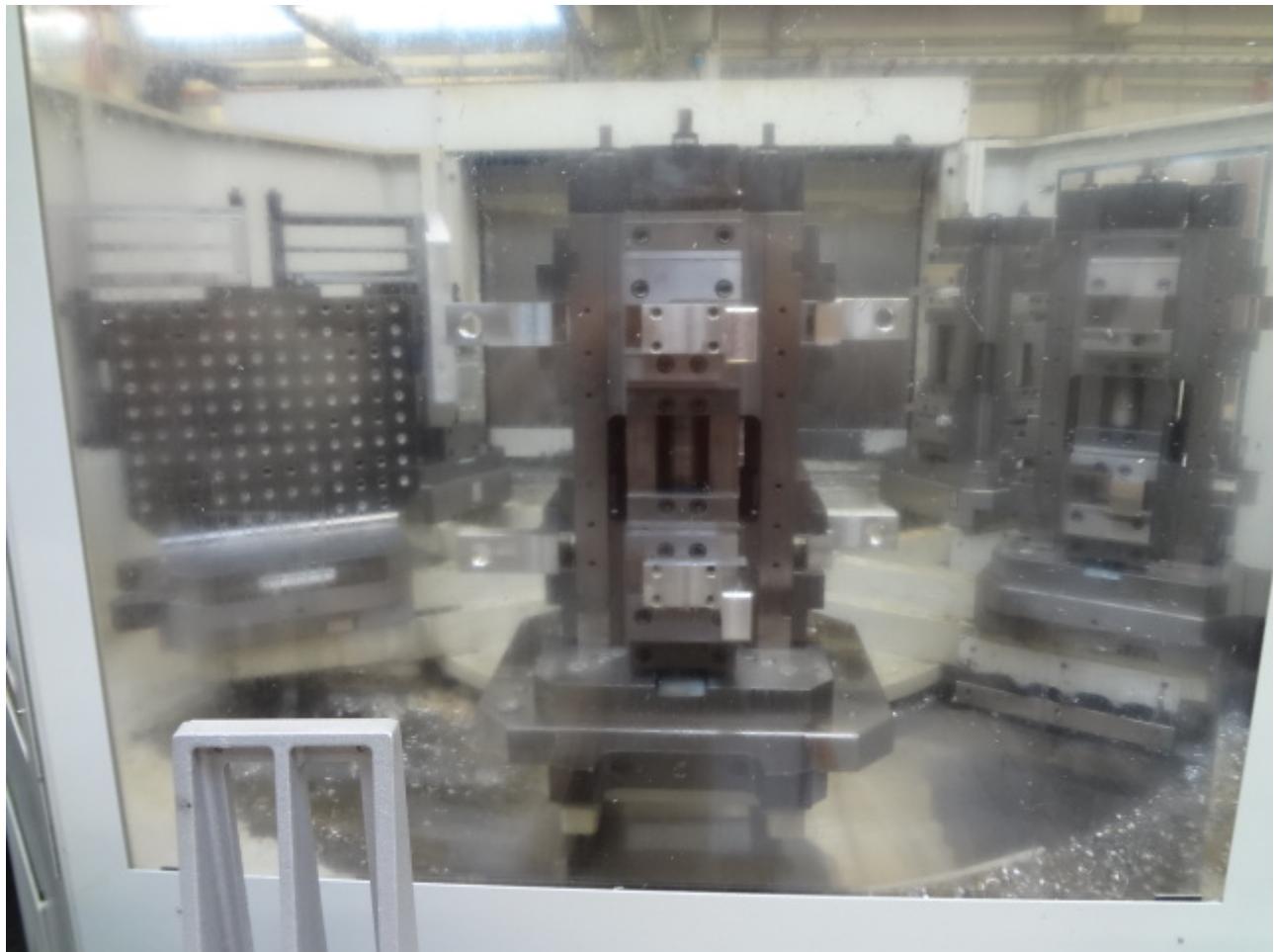
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11



12









16





**heckert**

starrag-heckert group

Heckert Werkzeugmaschinen GmbH  
D-09117 Chemnitz Otto-Schmerbach-Str. 15-17

Typ	<b>CWK 400 D</b>
Maschinen - Nr.	<b>18272</b>
Baujahr	<b>1999</b>
Temperaturbereich	<b>+5...35 °C</b>
Gesamtmasse	<b>12,5 t</b>



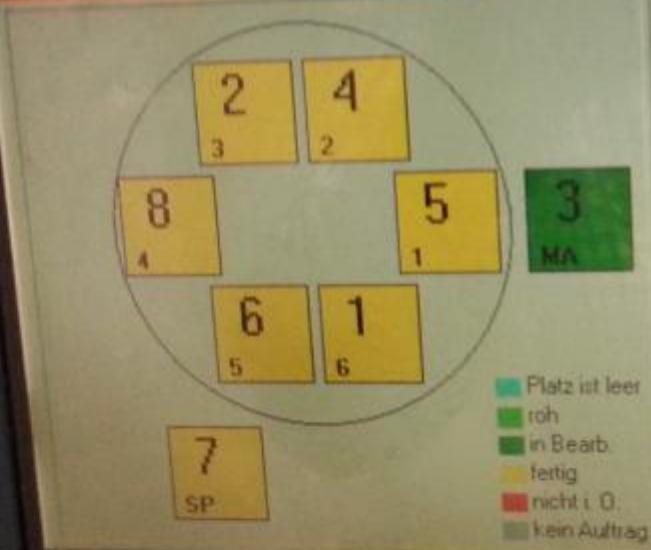
Made in Germany



SIEMENS

Intervall  
speicher  
Kanal aktiv  
Programm läuft  
510220 : Einlesespur bei Werkzeugwechsel

Speicherabbild



AUTOMAT

Palettenfolge

Aktiv: Palette3  
Folgebearbeitung: = 0

Meldungen

Aufträge Paletten- Einstellung



Benennung	Einheit	Wert:	Option
		CWK 400D	
		CWK500D	
<b>Positionsgenauigkeiten in den Achsen X, Y, Z nach VDI / DGQ 3441</b>			
Normalausführung	Positionierunsicherheit $P(T_3)$	µm	9
	Positionsabweichung $P_s$	µm	8
	Positionsstreubreite $P_{\text{streu}}$	µm	7
	max. Umkehrspanne $U_{\text{max}}$	µm	6
Hochgenauigkeits- ausführung	Positionierunsicherheit $P(T_3)$	µm	6
	Positionsabweichung $P_s$	µm	5
	Positionsstreubreite $P_{\text{streu}}$	µm	4
	max. Umkehrspanne $U_{\text{max}}$	µm	3

Benennung	Einheit	Wert	Option
		CWK 400D	
		CWK500D	
<b>Betreiberbedingungen</b>			
<b>Elektrotechnische Anschlußwerte</b>			
Werte sind ausführungsabhängig / detaillierte, maschinengebundene Angaben: Installationsplan (Teil Transport/Aufstellung/Inbetriebnahme)			
Netz	V	400 <small>10%</small>	
Betriebsspannung	Hz	50 <small>±1%</small>	
Frequenz	kVA	75	
Anschlußwert			
bei Normalausführung (Hauptantriebs-Leistung 24 kW)			
bei Ausführung mit erhöhter Beschleunigung	kVA	100	•
Dauerleistungsbedarf	kW	65	
bei Normalausführung (Hauptantriebs-Leistung 24 kW)			
bei Ausführung mit erhöhter Beschleunigung	kW	87	•
Steuerspannung	DC/Gleichstrom	V	24
<b>Umgebungsbedingungen</b>			
Temperaturbereiche	°C	+10 bis +35	
für Funktionsfähigkeit	°C	+20 <small>±2</small>	
für Nenngenauigkeit (Normalausführung)	°C	+20 <small>±1</small>	
für Nenngenauigkeit (Hochgenauigkeitsausführung)	°C	+20 <small>±1</small>	
zulässige Temperaturänderung	°C / Stunde	0,5	
zulässige relative Luftfeuchte	bei 20 °C	%	max. 80
zulässige Luftverunreinigung			es gelten die Werte der elektrotechnischen Ausrüstung
	Niederschlag (30d)	g/m <sup>2</sup>	1
	wasserlöslicher Staub	mg/m <sup>3</sup>	0,2
<b>Druckluftanschluß / Pneumatik</b>			
Anschlußdruck	bar	6,1 bis 10	
Luftverbrauch			
kurzzeitiger Spitzenverbrauch	m <sup>3</sup> / min	3,5	
Mittelwert bei Normaldruck	m <sup>3</sup> / Stunde	9	
Restölgehalt	mg / m <sup>3</sup>	≤0,1	
Restfeuchte	g / m <sup>3</sup>	≤2,75	
Verunreinigung			
Teilchengröße	µm	≤1	
Massenkonzentration	mg / m <sup>3</sup>	≤5	

Benennung	Einheit	Wert	Option
		CWK400D	CWK500D
		Sinumerik 840 D	
<b>Steuerung</b>			
<b>Massen / Raumbedarf</b>			
Anhängemasse	Maschine	kg	ca. 12.800 ca. 15.000
Länge	Normalausführung ca.	mm	4.600 4.850
Breite	Normalausführung ca.	mm	3.920 4.000
Maschinenhöhe (bei Kettenmagazin)	über Unterkante Bett	mm	2.900 2.950
Maschinenhöhe (bei Turmmagazin)	über Unterkante Bett	mm	2.700 2.950
Montagehöhe	über Unterkante Bett	mm	3150 3300
Höhe Unterkante Bett über Fußboden	Normalausführung ca.	mm	125
<b>Lärmemission</b>			
Lärmpegel	dBA	< 76 Prüfbedingungen: 1,6 m; Hauptgetriebe $n_{max}$ links und rechts; mittlerer Vorschub in allen Achsen nacheinan- der; Arbeitsraumschutz geschlossen, Mes- sung vor dem Spannplatz und am Einlegeplatz; Meß- gerät: Schallpegelmesser	

Benennung	Einheit	Wert	Option
		CWK 400D	CWK500D
<b>Hydraulik</b>			
Pumpe	Druck	bar	85 bis 90
	Förderstrom	l/min	22,5
Ölbehälter	Ölmenge	l	40
Antriebsmotor	Leistung	kW	4
	Anzahl der Kreisläufe	-	1
<b>Späneförderer</b>		mm	450
Nutzbreite	Standardausführung	mm	1050
Abwurfhöhe			
<b>Kühlaggregat</b>			
Kältemittel	Inhalt	-	R 134 A
Wasserbehälter		l	ca. 30
Zusatz gegen Korrosion		-	10% Anticorit

Benennung	Einheit	Wert	Option
			CWK 400D CWK500D
<b>Prozessschmierung</b>			
Anzahl der Kreisläufe	-	2	
<b>durch Spindelmitte</b>			
manuell schaltbar	l/min	30/27/24	•
	bar	30/40/50	•
schaltbar mit M-Befehl	l/min	30/27/24	•
	bar	30/40/50	•
über Düsen	l/min	50	
	bar	2	
<b>Schwalldusche</b>			
	l/min	ca. 70	•
Anzahl der Düsen am Dach	-	4	•
<b>Spülpistole</b>			
am Spannplatz	-		
Filterart	l	900	
mit	l	1350	•
Behälterinhalt	l	1250	•

Benennung	Einheit	Wert		Option
		CWK	400D 500D	
<b>Werkzeug-Kettenmagazin</b>				
Span-zu-Span-Zeit (gemessen nach VDI 2452)	s	5 **	6 **	
bei Elgang 40 mm/min	s	4 **	5 **	•
bei Elgang 82 mm/min	s	—	—	•
bei Elgang 100 mm/min	s	3,5 **	—	
			60	
<b>Anzahl der Werkzeugplätze</b>				
max. Werkzeugdurchmesser	mm	Ø 160 *		
bei freien Nachbarplätzen	mm	Ø 85		
bei belegten Nachbarplätzen	mm	Ø 125		•
bei freien Nachbarplätzen und Arbeitsspindel-Drehzahlerhöhung 24000 Upm	mm	350 *	400 *	
max. Werkzeugauskraglänge	mm			
max. Werkzeugmasse	kg	10		
bei Arbeitsspindel-Drehzahlerhöhung 24000 Upm	kg	5		•
max. Kippmoment (an Griffstelle des Basishalters)	Nm	10		
Gesamtmasse aller Werkzeuge im Speicher	kg	200		
max Unwucht der Werkzeuge bei unsymmetrischer Bestückung	kg	80		
<b>Werkzeug-Turmmagazin</b>				
Span-zu-Span-Zeit	s	5 **	6 **	•
bei Elgang 40 m/min	s	4 **	5 *	
bei Elgang 82 m/min	s	—	120/240	
<b>Anzahl der Werkzeugplätze</b>				
max. Werkzeugdurchmesser	mm	Ø 160		
bei freien Nachbarplätzen	mm	Ø 80		
bei belegten Nachbarplätzen	mm	Ø 125		
bei freien Nachbarplätzen und Arbeitsspindel-Drehzahlerhöhung 24000 Upm	mm	350		
max. Werkzeugauskraglänge	mm			
max. Werkzeugmasse	kg	10		
bei Arbeitsspindel-Drehzahlerhöhung 24000 Upm	kg	5		•
max. Kippmoment (an Griffstelle des Basishalters)	Nm	10		
max. Geschwindigkeit Q-Achse (Quer/Horizontalbewegung)	m/min	100		
max. Geschwindigkeit V-Achse (Vertikalsbewegung)	m/min	70		

- Einschränkungen bei max. Werkzeuglänge in Verbindung mit max. Werkzeugdurchmesser lauf Skizze Pkt 11.2.9.1 beachten!
- Bei Einsatz eines Winkelbohrkopfes und / oder Werkzeugaufnahme SK 40 erhöht sich die Span-zu-Span-Zeit um ca. 0,5 sec.

Bennung	Einheit	Wert	Option	
			CWK	400D 500D
<b>Arbeitsspindel / Hauptmotor</b>				
Durchmesser im vorderen Lager	mm	Ø75		
Werkzeugaufnahme		HSK-A63 DIN 69893		
		SK 40-AD DIN 69871		*
		Anzugsbolzen DIN 69872-19		
<b>Variante</b>				
<b>Motorspindel Starrag und HSK - A63</b>				
Drehzahlbereich	min <sup>-1</sup>	50 ... 15 000		
		40% ED	100% ED	
	kW	31	19	
Motorleistung	Nm	200	165	
Drehmoment				*
<b>Variante</b>				
<b>Motorspindel Starrag und SK 40</b>				
Drehzahlbereich	min <sup>-1</sup>	50 ... 10 000		
		40% ED	100% ED	
	kW	31	19	
Motorleistung	Nm	200	165	
Drehmoment				*
<b>Variante</b>				
<b>Motorspindel Starrag und HSK - A63</b>				
Drehzahlbereich	min <sup>-1</sup>	50 ... 10 000		
		40% ED	100% ED	
	kW	31	19	
Motorleistung	Nm	200	165	
Drehmoment				*
<b>Variante Hohlwellenmotor und SK 40</b>				
Drehzahlbereich	min <sup>-1</sup>	50 ... 10 000		
		40% ED	100% ED	
	kW	37	24	
Motorleistung	Nm	350	230	
Drehmoment				

Benennung	Einheit	Wert		Option
		CWK	400D 500D	
<b>Verstellwege</b>				
X - Achse (Ständerverstellung)	mm	650	750	
Y - Achse (Support-Senkrechtnverstellung)	mm	650	750	
Z - Achse (Tisch-Querverstellung)	mm	650	700	
<b>Verfahrbereich</b>				
min. Abstand Spindelvorderkante - Mitte Werkstückträger	mm	50	100	
min. Abstand Spindelmitte - Oberkante Werkstückträger	mm	30	80	
<b>lineare Vorschubachsen X / Y / Z</b>				
Vorschub	mm/min	0 ... 40 000 0 ... 82 000 0 ... 100 000		•
Eilgang	m/min	40		
	m/min	82		•
	m/min	100		•
technologisch verwertbare Vorschubkraft 60% ED	kN	12*		
100% ED	kN	10*		
Meßsysteme:				
linear, optisch-inkremental, abstandscodiert				
Genauigkeitsklasse	µm	±5		
Teilungsperiode der Strichgitterteilung	µm	20		
Eingabe- und Anzeigefeinheit	µm	1		
Beschleunigung X/Y/Z	bei Eilgang 40m/min			
	m/s <sup>2</sup>	7		
Eilgang 82m/min bei Hohlwellenantrieb	m/s <sup>2</sup>	9,3 / 9,6 / 10		•
bei Motorspindel	m/s <sup>2</sup>	4 / 5,5 / 4,5		•
Eilgang 100m/min	m/s <sup>2</sup>	15/15/12		•

\* Beachten Sie die Einschränkung der Vorschubkraft  
(siehe Bild 1: Diagramm Zulässige Vorschubkraft im oberen Y-Bereich)

Benennung	Einheit	Wert:		Option
		CWK	400D 500D	
<b>NC-Drehtisch / Drehachse B</b>				
max. Drehzahl	min <sup>-1</sup>	25		
Eingabe- und Anzeigefeinheit	Grad	0,001		
zul. Tangentialmoment (Tisch geklemmt)	Nm	3000		
zul. Tangentialmoment bei Dreharbeiten	Nm	530 bei 100% ED 1000 bei 60% ED		
max. Kippmoment ab Oberkante Palette	Nm	5000		
Positionierzeiten	s	0,8		
45°	s	1,2		
90°	s	2,0		
180°	s	12"		
Normalausführung	Positionunsicherheit P (T <sub>p</sub> )	10"		
max. Positionsstreuubreite P <sub>max</sub>		6"		
max. Umkehrspanne U <sub>max</sub>		6"	•	
Hochgenauigkeitsausführung	Positionierunsicherheit P (T <sub>p</sub> )	5"	•	
max. Positionsstreuubreite P <sub>max</sub>		3"	•	
max. Umkehrspanne U <sub>max</sub>				

11.5 Technische Daten

Benennung	Einheit	Wert		Option
		CWK	400D	
<b>Palette</b> (am Spannplatz drehbar)				
Aufspannfläche	mm x mm	400 x 400 400 x 500	- -	•
	mm x mm	-	500 x 500 500 x 630	•
max. Belademasse pro Palette (mittig)	kg	400	500	
bei Elgang 82 m/min	kg	300		•
bei Elgang 100 m/min	kg	200		•
zul. Moment bei außermittiger Last	Nm	200		
Höhe der Werkstück-Aufspannfläche über Unterkante Bett (Spannplatz)	mm	1000		
Richtbohrung - Durchmesser	mm	$\varnothing 20$ H 6		
Abstand zur Tischmitte	mm	150 $\varnothing 0,013$	200 $\varnothing 0,013$	
Aufnahmebohrung ohne Spannhydraulik in Verbindung mit Spannhydraulik	mm	$\varnothing 50$ H 6 $\varnothing 20$ H 6		
Befestigungsgewinde (Normalausführung)		43 x M12	23 x M12	
T-Nut (ähnlich DIN 650)	mm	14		
Werkstück-Durchlaßhöhe	mm	750	900	•
max. Störkreis	mm	$\varnothing 700$	$\varnothing 800$	
Spannhydraulik für Werkstückspannung		3 Anschlüsse		•
<b>Automatischer Palettenwechsel</b>				
Anzahl der wechselbaren Paletten	-	2		
max. Palettenwechselzeit bei Normalausführung	s	8	9	
bei Ausführung mit Spannhydraulik mindestens	s	10		

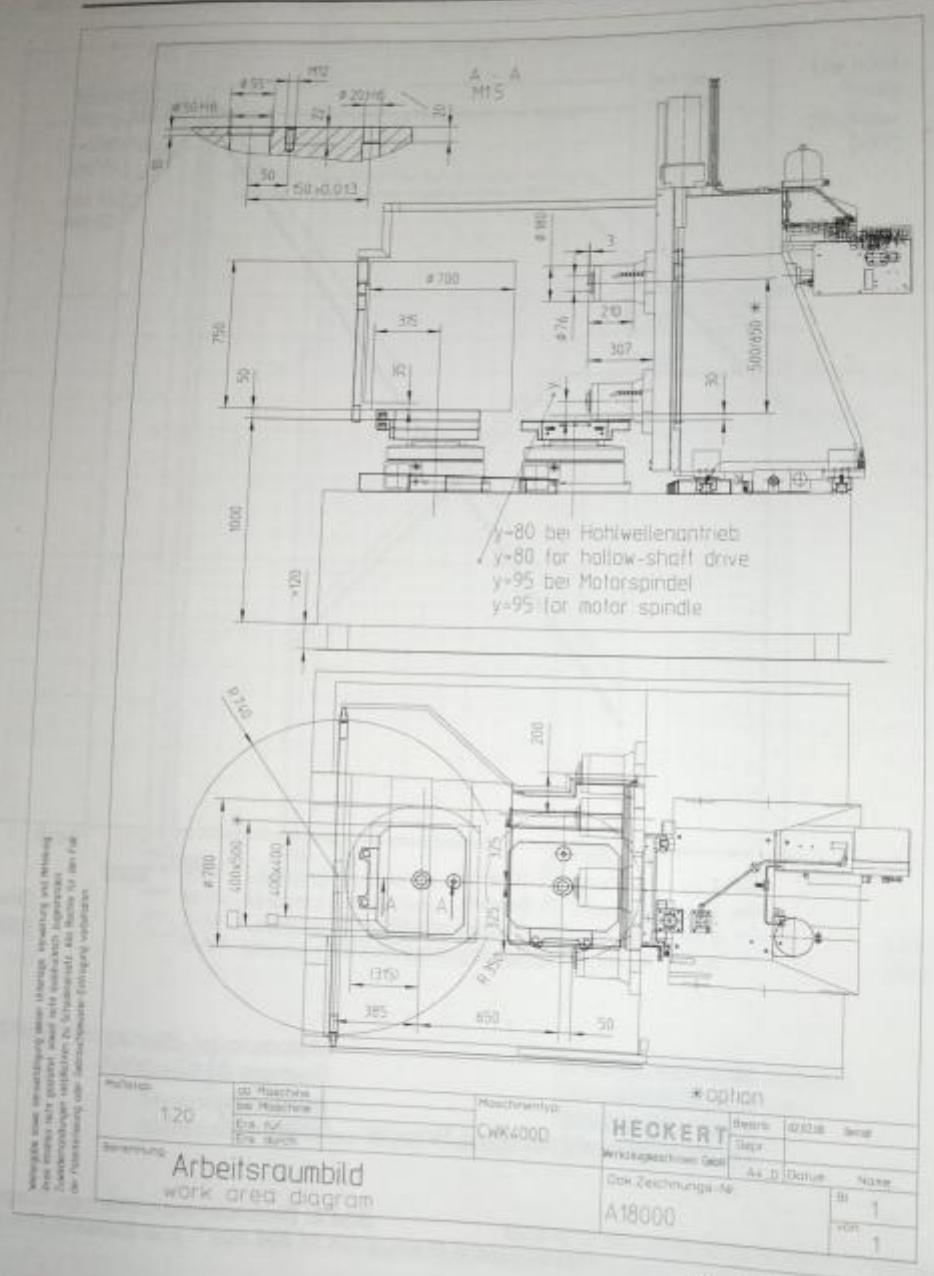
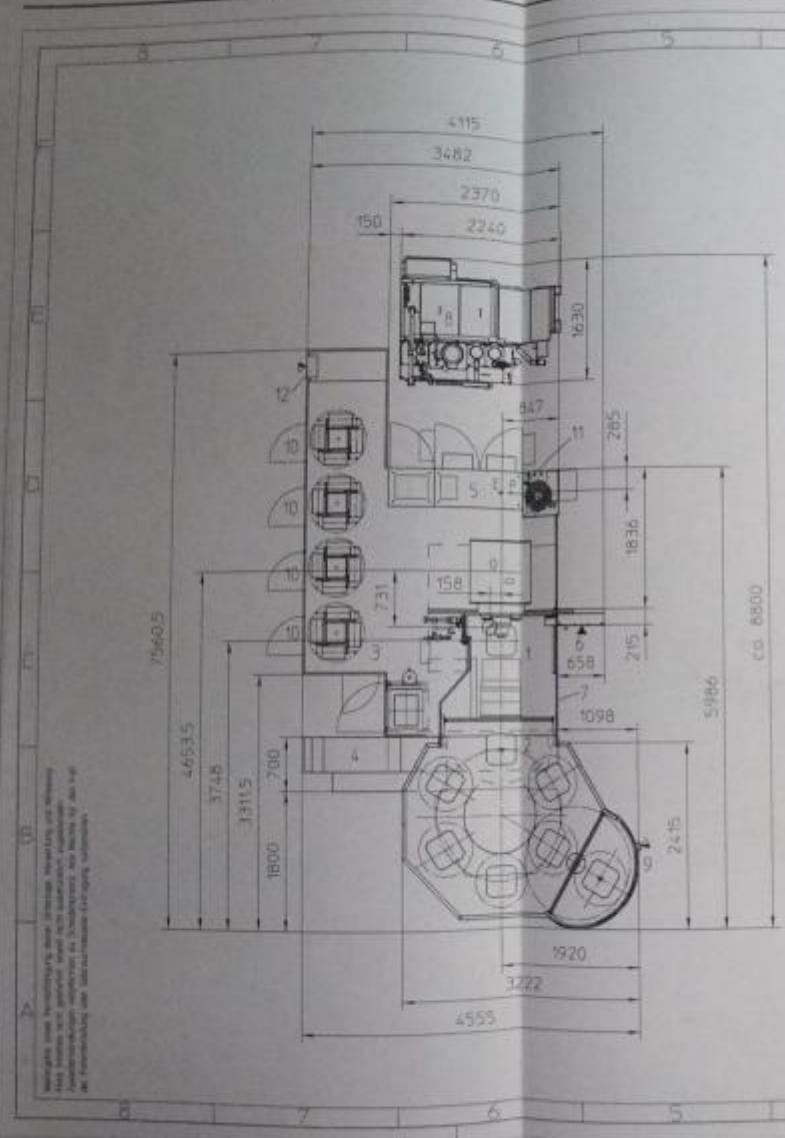


Bild 6: Arbeitsraumbild

1840g 07.9.2001

Betriebsanleitung



18409 07 9 2001

Betriebsanleitung

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## Transport/Aufstellung/Inbetriebnahme Abschnitt 5

HECKERT  
CWK400D /500D

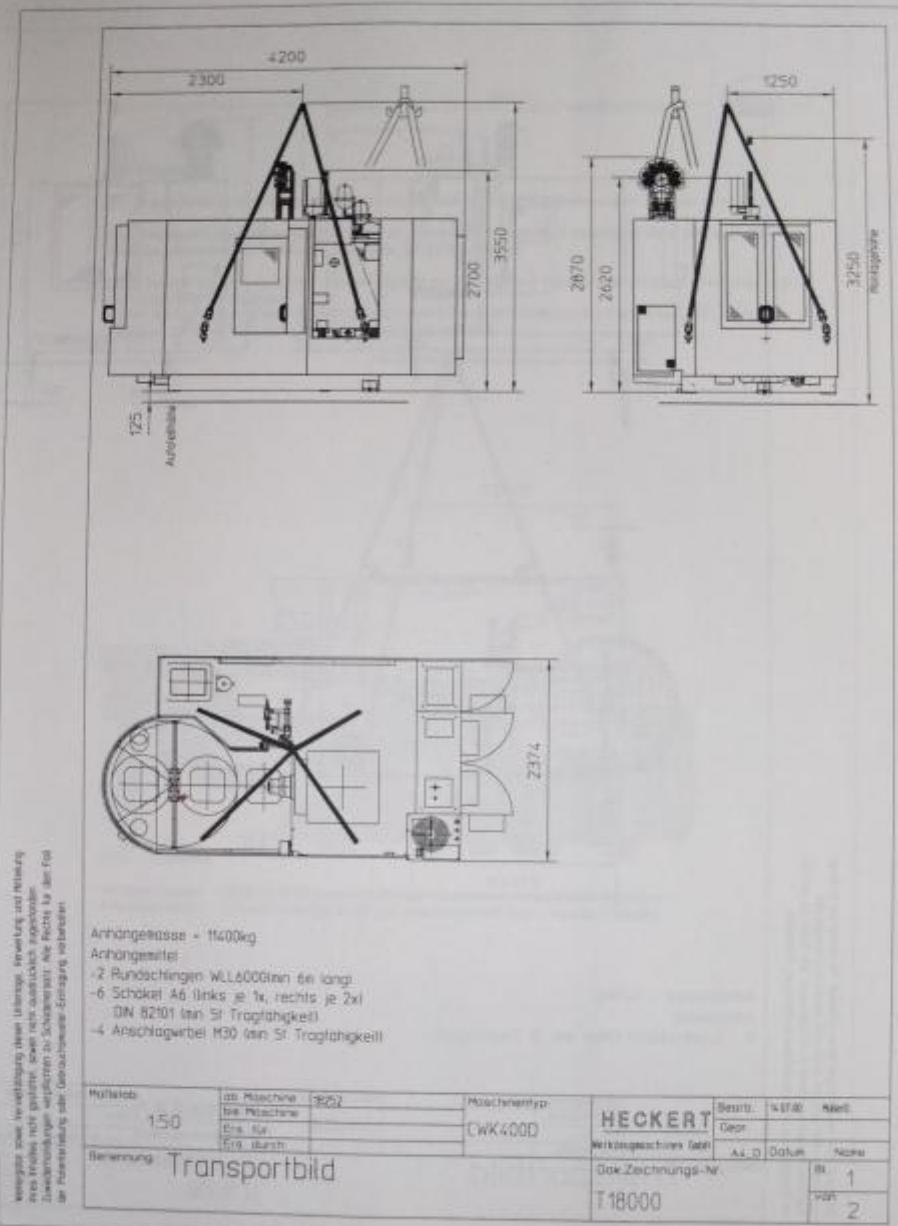


Bild 6: Transport Maschine Bl. 1

18409 16.08.2001

Betriebsanleitung

27 May 30

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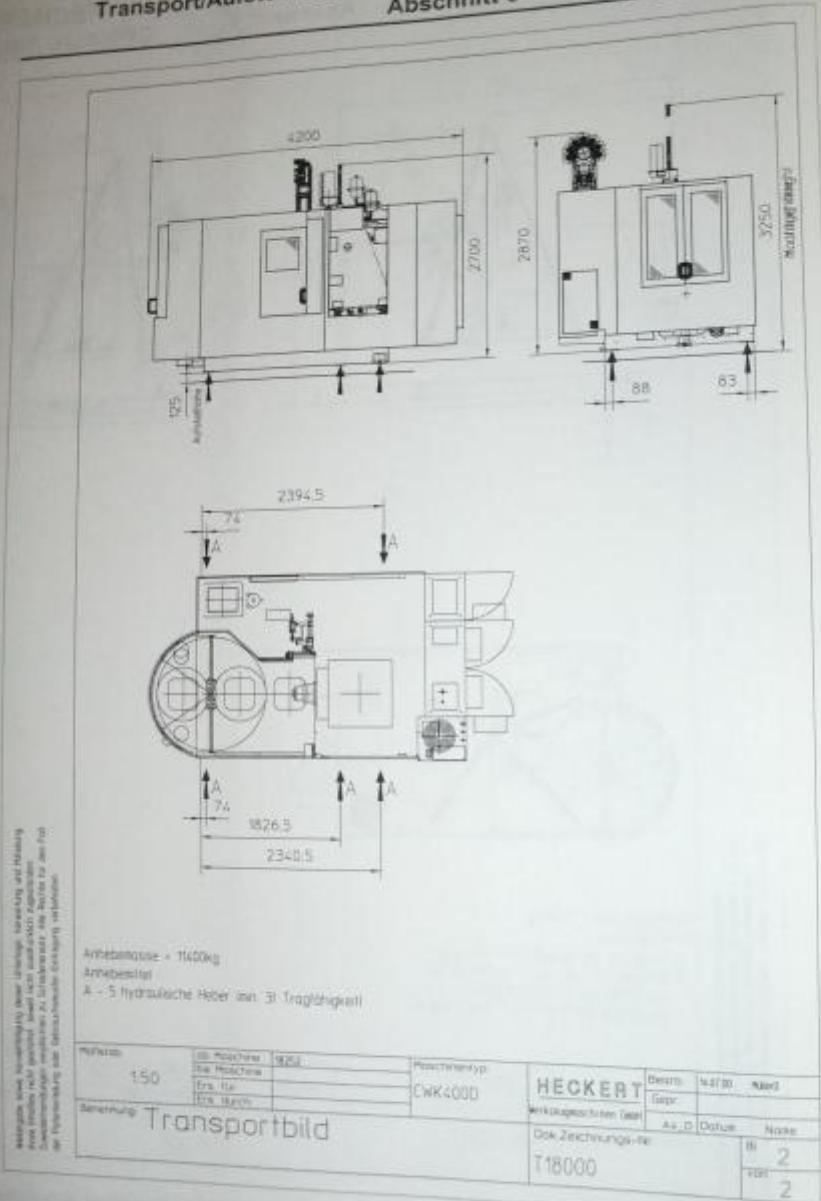


Bild 7: Transport Maschine Bl. 2

18409 16.08.2001

Betriebsanleitung

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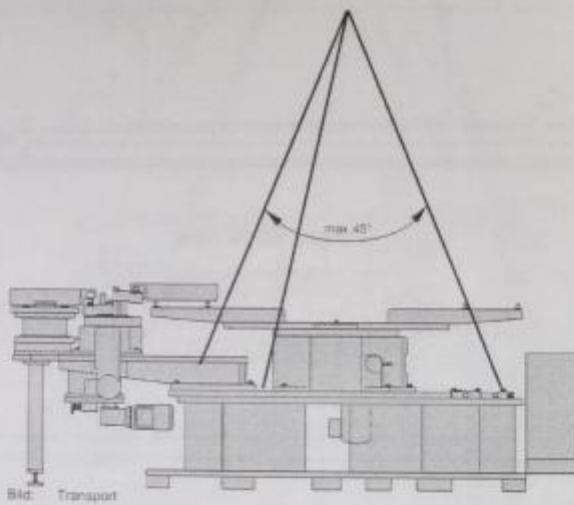
## 2. Transport

Der Palettenpool ist eine kompakte Baugruppe die nach der Inbetriebnahme in dem Zustand verbleibt.

Das Anhängen des Palettenpool darf nur an den mitgelieferten M20 Anschlagwirbel erfolgen. Das Einsetzen anderer Anhängeschrauben ist nicht zulässig!

Die 6 Schrauben zwischen Verschiebeplatte und Grundkörper müssen beim Transport fest angezogen sein (siehe Bild Grundgestell).

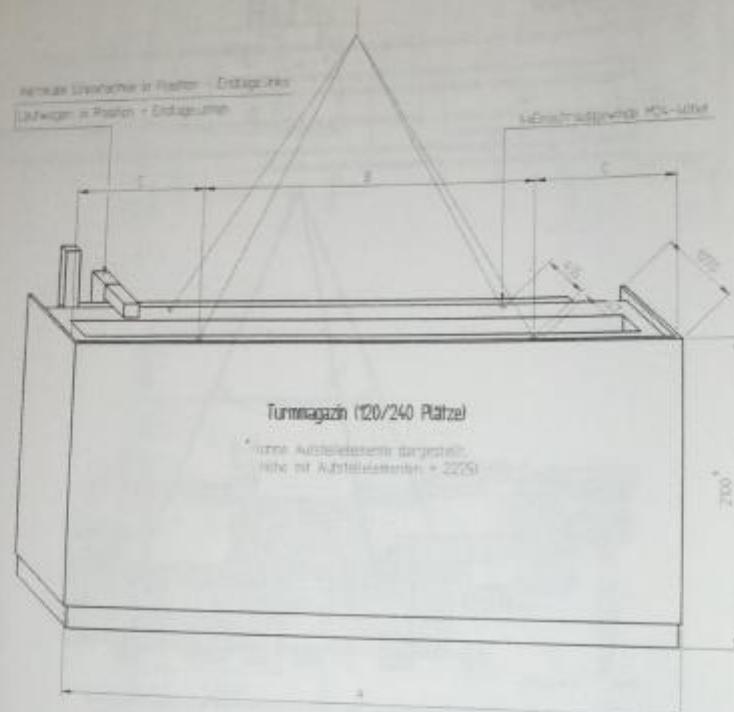
Halten Sie die einschlägigen Unfallverhütungsvorschriften beim Transport des Palettenpool ein, die unter anderem den Aufenthalt unter schiebenden Lasten verbietet.



Anhängemasse: 3800 kg (Palettenpool komplett mit elektromechanischen Wechsler)  
Anhängemitte: 3 Anschlagwirbel M 20 (pro Anschlagwirbel sind 2 Tonnen zulässig)

Bild 8: Transport Palettenpool

Anhängerbild-Krantransport



Turmmagazin-Typ	A mm	B mm	C mm	Masse kg
240 Plätze	4250	2906	377	1260
120 Plätze	2970	965	377	2780

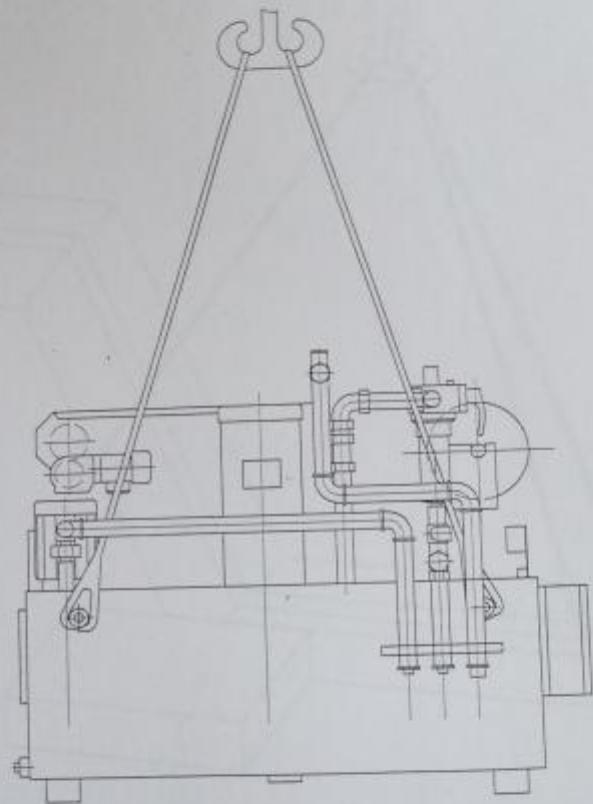
Bild 9: Transport Turmmagazin

18409 16.08.2001

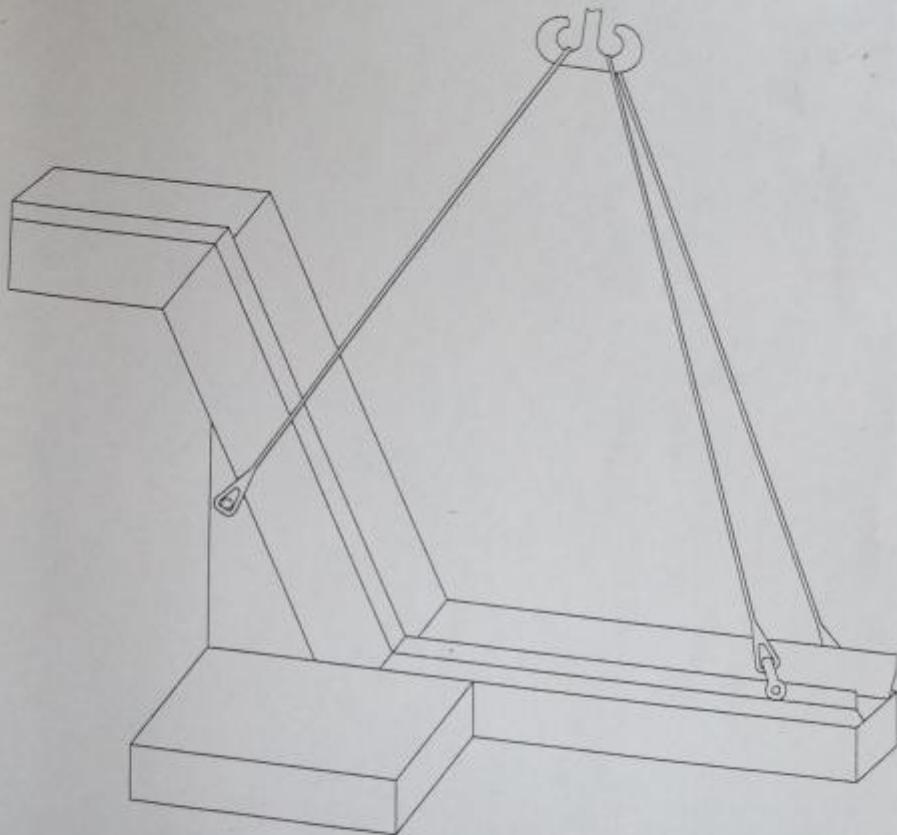
Betriebsanleitung

D

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Projekt-Nr.	ab Maschine	2000	Maschinen-Nr.	Bearb.	700/1000
120	ab Maschine		CWK 1000	Ges.	11
	frs. für				
	frs. durch				
Bezeichnung			Sachnummer	Std	7
TRANSPORTBILD, KÜHLMITTELBEHÄLTER			T20000	inh	9



With Ever More  
To The New Mill



The new HECKERT CWK 500 D Centres have been developed to meet the demands of modern production. Using motor technology with speed ranges of up to 15,000 rpm and high static accuracy, the machining centres can meet the customers' requirements to a high extent. The CWK 500 D has the highest dynamics in its class, achieving top rates of up to 100 mm/min. The machining centres are able to reach values with up to 82% higher productivity. Innovative ideas have been implemented in tool management, the well-known tool magazine with max. 240 tools, developed a new magazine with 60 pockets between magazine and tool magazine. This also substantially reduces the time from 1.5 sec. and 3.5 sec. to 1.5 sec. and 3.5 sec.

## All Around A Direct Hit

**1** Installation without any need for foundation

thanks to compact design with T-type bed and columns with reduced mass

**2** Safe and extremely fast part removal

from the working zone thanks to start-bed design, part conveyor arms and part conveyor as preconditions for dry machining

**3** Highest positioning accuracies

$P \pm 0.006$  mm and  $P_{max} \leq 0.004$  mm in all linear axes by means of linear motion guideways

**4** Highest rapid traverse rates and short controller acting times

thanks to digital AC servo drives with pre-loaded ball lead screws

**5** Dynamic package 1 g (optional)

with rapid traverse rate of 82 m/min, acceleration rate of 10 m/s<sup>2</sup> and motor-driven spindle of 15,000 rpm

**6** Dynamic package 1.5 g (optional)

for CWK 400 D) with rapid traverse rate of 100 m/min, acceleration rate of 14 m/s<sup>2</sup> and motor-driven spindle of 15,000 rpm

**7** Main drive

in variants with motor-driven spindle  
- driving power ratings of up to 21 kW, speed range of up to 10,000 rpm, steep-taper tool receptor AD 40 or hollow-shank taper HEK 63

- driving power ratings of up to 31 kW, speed range of up to 15,000 rpm, HEK 63 tool receptor

- driving power ratings of up to 60 kW, speed range of up to 24,000 rpm, HEK 63 tool receptor

or with hollow-shaft-type motor  
- driving power ratings of up to 35 kW, torque up to 335 Nm, speed range of up to 10,000 rpm, steep-taper tool receptor AD 40

**8** Part changeover time 8 to 9 sec. thanks to hydraulic rotary changer

**9** Rotatable clamping station with 4- $180^\circ$  indexing facility for operator friendly workpiece setting work while the machining cycle is running

**10** NC rotary table for multitasking and complete machining to satisfy highest accuracy demands ( $P \leq 8^\circ$ ,  $P_{max} \leq 1^\circ$ ) with coupling unit for hydraulically workholding fixtures

**11** High-performance in-process control and monitoring facilities use of Siemens 840 D CNC continuous-path controller in 32-bit technology or, as an option, Fanuc 16i including comprehensive control and monitoring facilities

**12** Tool handling with chain-type magazine, change-over times 3.5 to 4 sec., parallel tool location between magazine and main spindle, drive by means of AC servo motor to reduce the availability times for segmental tool and the chip-removal times

**13** Tool handling with tool tower magazine

space-saving option with regard to chain-type magazine for increased tool demands of up to 240 pockets with smallest installation area and tool changeover in parallel to production time

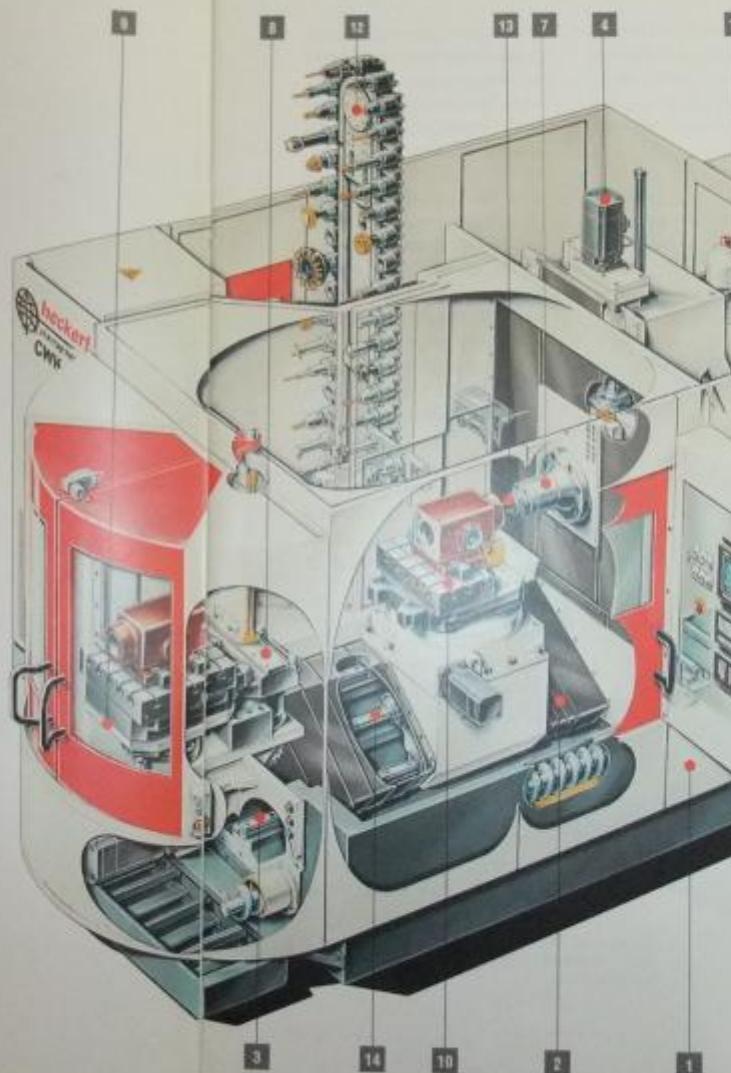
**14** Coolant system

wet machining with constant supply through nozzles or through spindle centre with a delivery pressure rating of up to 50 bar or dry machining with minimum-quantity lubrication

**15** Low-maintenance grease lubrication

for motor-driven spindle, ball lead screws and linear motion guideways

**16** Conversion into manufacturing cells and flexible manufacturing systems with circular and linear magazines for workpiece pallets



## Economy And Ecology Form An Optimal Entity

- The compact design of HECKERT CWK 400 D and CWK 500 D centres with a T-type bed, carrying all major machine elements in the condition for transporting the machine as a single complete entity, for installation without any need for foundations and instant readiness for use. This saves foundation, transportation, and assembly costs and makes sure that tool production can be started even earlier.
- All major machine elements feature excellent shock absorbing qualities and a very limited heat expansion to ensure vibration-free machining with high performance.

■ To ensure fast and safe swarf removal from the working zone, the machine bed has been configured in slot-bed design. The consequential prevention of heat accumulation will create ideal conditions for dry machining.

■ Extremely high running, positioning and permanent accuracies are ensured by optimally dimensioned linear motion guideways in all linear axes.

■ Incremental, direct linear encoder systems with distance coding have been encapsulated in aluminum casings and

are pressurized with compressed air. So, the encoder systems are protected from swarf, coolant and contaminations. An incremental encapsulated angular position encoder system is used for the NC rotary axis.

■ Manufacturing tolerance deviations and temperature fluctuations can be compensated for in conjunction with the CNC controller. In the stage of extension featuring enhanced machining accuracy, a positioning deviation of  $P \leq 0.006$  mm and a positioning variation of  $P_{\text{max}} \leq 0.004$  mm in all linear axes and  $P_{\text{max}} \leq 5^\circ$  in the rotary axis can be achieved. So, accuracies in the IT5/IT6 tolerance class can be obtained at the workpiece.

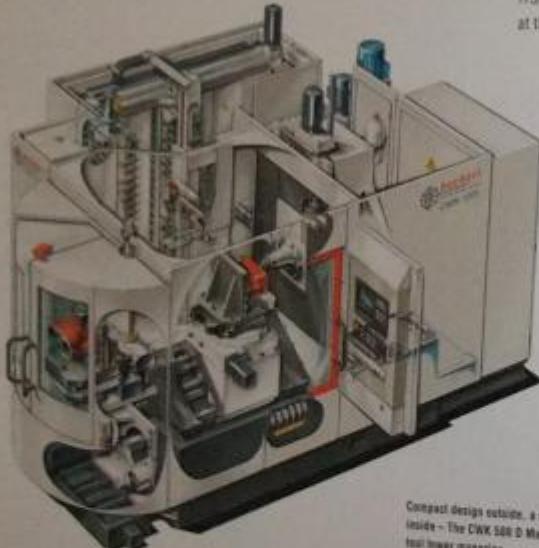
■ The technical concept of the HECKERT CWK 400 D and CWK 500 D consistently applies all necessary considerations for strict adherence to ecological requirements. Total-loss oil lubrication has become a thing of the past. Thanks to grease lubrication for main spindle, ball lead screws and linear motor guideways, maintenance requirements have been reduced quite considerably.

■ With the machine being sealed off the shop floor, any ingress of coolant and hydraulic oil is avoided. This has been achieved by a machine bed which carries all functional machine elements and is hermetically sealed.

■ Faseless coolant purification with vacuum edge strainer and return flow filter for the high-pressure circuit does away with cost-intensive special refuse disposal requirements.

■ In accordance with environment and operator-friendliness, a splash shower in the working zone with a coolant volume rate of 70 l/min, an air-blast gun at the clamping station for cleaning of workpiece and fixture and an emission extraction can be incorporated in the machining centres.

■ A clear view of the working zone is always ensured by a pneumatically operated, rotating inspection window in the working-zone safety door.



Compact Design outside, a variety of innovations inside - The CWK 500 D Machining Centre with four tower magazines

## ■ How A Reduction In Idle Times Can Be All Important



HECKERT CWK 400 D and CWK 500 D Machining Centres  
After heat treatment for light-metal machining of engine components

Optimal cutting conditions with coolant supply  
through spindle centre and through external nozzle



### ■ Main drive

A characteristic of the new HECKERT CWK 400 D and CWK 500 D Machining Centres is the highly dynamic behaviour of the main drive. With a mass-reduced and grease-lubricated motor-driven spindle, speeds of up to 10,000 rpm, 15,000 rpm and 24,000 rpm at power ratings of 31 kW can be reached optionally.

Even for heavy-duty cutting work, HECKERT offers another solution. A hollow shaft-type motor ensures power ratings of 35 kW at torques of 335 Nm.

Optimal conditions are obtained for wet machining. Coolant supply is optionally possible through external, adjustable ball nozzles or through spindle and tool centre. Absolute swarf removal is guaranteed during core drilling with a delivery pressure rate of up to 50 bar. Ideal machining results are achieved in dry machining thanks to the minimum-quantity lubrication.

Clamping and unclamping of tools with steep-taper receptor 40 or hollow-shaft taper HSK-63 function quickly and safely by means of Belleville spring pack and hydraulic cylinder. Blasting of spindle taper and internal coolant supply of tools with compressed air during the automatic tool changeover cycle avoids contamination and prevents negative influences on the machining quality.

### ■ Feed drive

Digital AC servo motors in combination with preloaded ball lead screws ensure short positioning times, minimized controller acting times, maximum rapid traverse rates, and a high stability over the whole range of feed rates. They feature the cost-saving option to the linear drives and reduce idle times above average with rapid traverse rates optionally from 40 mm/min up to 100 mm/min and acceleration rates of up to 15 m/s<sup>2</sup>. Such problems of linear drives as mastering of magnetic forces, expensive cooling and mass-dependent power capacity are excluded when using the rotary HECKERT drives.

Even more dynamics can be achieved by the optionals:

#### Dynamic package 1 g

(CWK 400 D and CWK 500 D)

- rapid traverse rate 82 mm/min
- acceleration rate 10 m/s<sup>2</sup> in all linear axes
- motor-driven spindle with max. 15,000 rpm
- hollow-shank taper HSK-A63
- chip-to-chip time 4 sec.

#### Dynamic package 1.5 g (CWK 400 D)

- rapid traverse rate 100 mm/min
- acceleration rate of up to 15 m/s<sup>2</sup>
- motor-driven spindle with max. 15,000 rpm
- hollow-shank taper HSK-A63
- chip-to-chip time 3.5 sec.

### ■ Pallet changeover

Pallet changeover too is safe, comfortable and ultra-fast. A hydraulically operated rotary pallet changer ensures exchange

of pallets within a time of 10 seconds. Workpieces are clamped in the clamping station and unclamped at the clamping station. The pallet changeover takes place in the standard design of the machine with its 4 × 90° indexing table. An NC rotary table is of course available for machining operations. The table is fitted with a high-pressure system to ensure a positioning dynamics and a position variation of 0.01 mm. The operator comfort console satisfies highest quality requirements.

The NC rotary table is available with a coupling and a high-pressure stage to support the holding fixtures.



## Highest Innovation During Tool Changeover

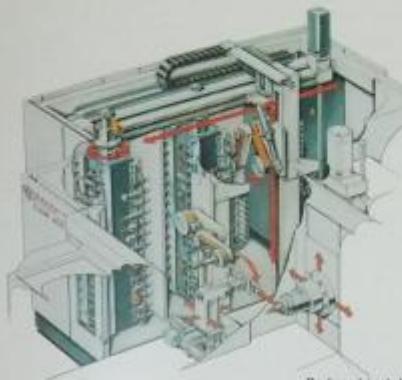
The tool handling is optimally matched with the machining job. Whether equipped with chain-type magazines for 80 tools or with tool tower magazine for 120 or 240 tools, the chip-to-chip time with dynamic package is only 3.5 to 4 sec. for tools of 10 kg in weight, 160 mm in diameter and up to 400 mm in length. The chip gripper is located outside the machining area and therefore not subject to coolant and swarf ingress. The enhanced peripheral speed of crane-type magazine will reduce the availability time of unpassive tool to 1.5 sec. This is of particular importance for light-metal machining.

The tool tower magazine, featuring highest tool density at minimum space requirements, reduces setup times, optimizes sequences of operation and enhances operator comfort.

Arrangement of tools in share-type magazine  
is parallel to the main spindle  
ensures a chip-to-chip time of 2.3 sec.



## Advantages of tools as against chain-type magazines



Dynamic tool changeover  
between main spindle and  
tool tower magazine

Reduced installation space

– Highest tool density at  
0.25 m<sup>2</sup> installation space

– Full occupation of space  
without vacant positions

Reduced setup times

– Manual tool changeover  
from magazine during  
within the automatic cycle

– Each tool can be  
located in any position

– Full occupation of  
space without adjacent

Tool tower magazine for  
max. 120 or 240 tools with highest tool  
density at minimum space  
requirements



## Flexible Manufacture Can Be Extended

### ■ Linear magazine

A track-bound workpiece pallet transporter, clamping station for setup work, storage locations in linear arrangement for intermediate storage of workpiece pallets and a cell controller are included in the linear magazine.

The transporter featuring a traverse speed of 60 mm/min as well as short acceleration and deceleration times guarantees short setup times.

The independent NC controller of transporter increases operator comfort and reduces setup expenditure. The transverse conveyor at the transporter ensures double-sided loading and unloading of workpiece pallets and thus a high flexibility in cell structure.

When the storage locations are arranged in 2 or 3 tiers, the transporter simultaneously takes over the function of a pick-and-place device.

Setup work at the clamping station is carried out quickly, safely and under good ergonomic conditions. For clamping, positioning and unclamping of workpieces, for resetting the fixtures and for simple measuring operations, the clamping station can be rotated and indexed  $4 \times 90^\circ$ .

A protection device designed as lifting cage with electric drive and locking functions will increase labour safety and ease of operation.

The storage locations guarantee limited operator attendance for intermediate and buffer storage and can be arranged in one tier or in 2 or 3 tiers to save space.

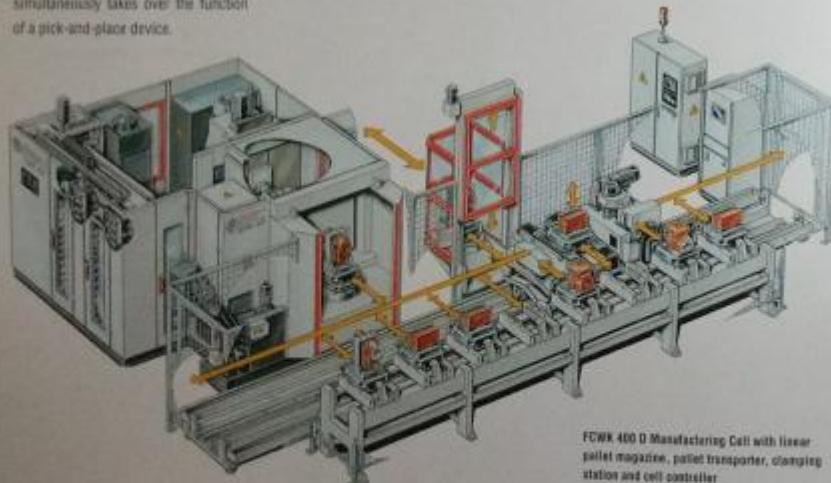
### ■ Circular magazine

The circular magazine in compact and, thus, space-saving design has got 6 storage locations and 1 clamping location and is driven by means of an AC servo motor.

To ease operation, the incorporated clamping station can be rotated and indexed for workpiece setup work.

The workpiece pallets are quickly and safely transported from the clamping station to the circular magazine according to the rotary-changer principle.

Following the same principle, the pallets

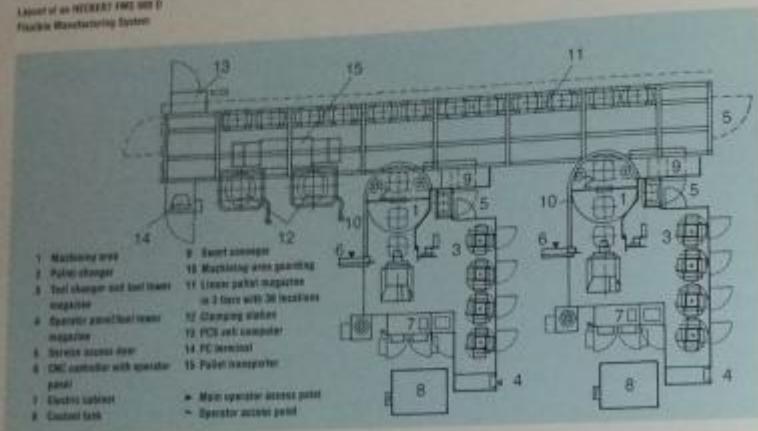


FCWK 400 D Manufacturing Cell with linear pallet magazine, pallet transporter, clamping station and cell controller



## Machining Area

Layout of an HECKERT CWK 400 D  
Flexible Manufacturing System



### Control and monitoring facilities

Comprehensive control and monitoring facilities are at choice for the HECKERT CWK 400 D and CWK 500 D Machining Centers as a precondition for semi-unattended manufacture and for reducing manual inspection work.

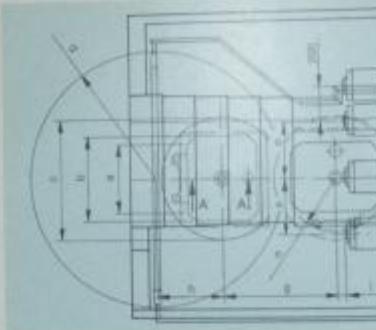
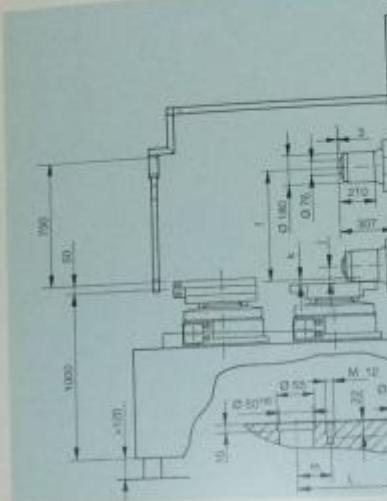
The target value and remaining life expectancy per tool are indicated on the CNC monitor screen for monitoring of

tool lifetime and consequential steps are automatically initiated upon any excess thereof. The main drive power rating is monitored for wear detection at the cutting edges of tool.

The speed given in the tool list for each tool is permanently monitored to avoid any overspeeding.

Direct tool break monitoring is ensured by means of break detector with pneumatic cylinder.

Direct tool break monitoring  
at break detector



CWK 400 D

a	mm	400 × 400
b (optional)	mm	(500 × 400)
c	mm	700
d	mm	8740
e/ longitudinal travel	mm	× 325
f/ vertical travel	mm	500 (550)
g/ transverse travel	mm	650
h	mm	385
i	mm	50
j	mm	95 for motor-driven spindle (80 for hollow-shaft motor)
k	mm	30
l	mm	150 ± 0.013
m	mm	50
n	mm	8110

Values in brackets = special execution

## Technical Data

	CKW 400 D	CKW 400 D with dynamic package 1g	CKW 400 D with dynamic package 15g	CKW 500 D with dynamic package 1g	CKW 500 D with dynamic package 15g
<b>NC rotary table</b>					
Clamping surface/light pattern (table DIN 35207)	mm	400 = 400 (300 = 400) / 400 = 400 (300 = 400)	400 = 400 (500 = 400)	500 = 500 (630 = 500)	500 = 500 (630 = 500)
Input and display resolution	degrees	0.001	0.001	0.001	0.001
Max. load	kgf	400	300	500	300
Max. speed	rpm	25	25	25	25
Workpiece swing diameter	mm	700	700	700	700
<b>Automatic pallet changer</b>					
Number of changeover pallets		2	2	2	2
Max. pallet changeover time	sec	8	8	8	8
<b>Transverse range</b>					
Source, main (X-axis)	mm	650	650	650	650
Spindle head, vertical/Y-axis	mm	500 (650)	650	650 (750)	650 (750)
Total, transverse (Z-axis)	mm	650	650	700	700
<b>Max. spindle/Motor-driven spindle</b>					
Power rating at 100 % duty cycle	kW	19	19	19	19
Power rating at 40 % duty cycle	kW	31	31	31	31
Torque at 100 % duty cycle	Nm	165	165	185	185
Torque at 40 % duty cycle	Nm	200	200	200	200
Tool recognition		SK 40 DIN 69821	HSK 03	SK 40 DIN 69821	HSK 03
Tool A		HSK 03		HSK 03	
Speed range	rpm	50...10000 (10000)	50...15000	50...15000	50...15000
Diameter of front bearing	mm	70	70	70	70
Increased power (using hollow-shaft motor optional)					
Power rating at 100 % duty cycle	kW	24	24	24	24
Power rating at 40 % duty cycle	kW	35	35	35	35
Torque at 100 % duty cycle	Nm	230	230	230	230
Torque at 40 % duty cycle	Nm	335	335	335	335
High speed package (optional)					
Max. spindle/drive spindle	rpm		24000		24000
<b>Automatic tool changer</b>					
Chain-type magazine					
Magazine pockets		80	60	80	60
Max. tool diameter	mm	160	160	160	160
Max. tool length	mm	350	350	400	400
Max. tool weight	kg	10	10	10	10
Max. off-torque	Nm	10	10	10	10
Max. chip-to-chip time	sec	5	4	3.5	4
Tool tower magazine (optional)					
Magazine pockets		120/240	120/240	120/240	120/240
Other data same as chain-type magazine					
<b>Transverse rates</b>					
Feed rate range, velocity variable	mm/sec	0...40	0...82	0...100	0...40
Right transverse rate	mm/sec	40	82	100	40
Acceleration rate	mm/sec <sup>2</sup>	7	10	15/12 for 2 axes	7
<b>Coolant system</b>					
Supply through spindle centre					
Volume	l/min	24 (30/27/24)	34 (30/27/24)	24 (30/27/24)	24 (30/27/24)
Pressure	bar	10 (30/40/50)	10 (30/40/50)	10 (30/40/50)	10 (30/40/50)
Supply via杂志					
Volume	l/min	50	30	50	50
Pressure	bar	2	2	2	2
Coolant tank capacity	l	550 (900)	350 (900)	550 (900)	350 (900)
<b>Machine accuracy according to VDI/DSG 3441</b>					
Linear axes X, Y and Z					
Positioning deviation P	mm	≤ 0.01 (0.006)	≤ 0.01 (0.006)	≤ 0.01 (0.006)	≤ 0.01 (0.006)
Positioning variation Pmax	mm	≤ 0.037 (0.004)	≤ 0.037 (0.004)	≤ 0.037 (0.004)	≤ 0.037 (0.004)
NC rotary table					
Positioning deviation P	mm	≤ 12 (6)	≤ 12 (6)	≤ 12 (6)	≤ 12 (6)
Positioning variation Pmax	mm	≤ 10 (5)	≤ 10 (5)	≤ 10 (5)	≤ 10 (5)
Net weight	kg	12800	12800	12800	15000
<b>CNC controller type</b>					
Siemens 840 D (Parus 16.4)	Siemens 840 D (Parus 16.4)	Siemens 840 D (Parus 16.4)	Siemens 840 D (Parus 16.4)	Siemens 840 D (Parus 16.4)	Siemens 840 D (Parus 16.4)
<b>Circular magazines (optional)</b>					
Number of storage locations		8	6	6	8
Design of changing stations				rotatable and rotatable 4 × 90°	
Number of pallets in total system, max.		8	8	8	8
<b>Linear magazine (optional)</b>					
NC transporters				track-bound, with transverse conveyor and lifting device	
Transverse speed, approx.	mm/sec	60	60	60	60
Clamping station				rotatable and rotatable 4 × 90°	
Storage locations, optional design		1, 2 or 3 tiers	1, 2 or 3 tiers	1, 2 or 3 tiers	1, 2 or 3 tiers
Number of tiers	12/24/36	12/24/36	12/24/36	12/24/36	12/24/36
Number of pallets in total system, max.	14/26/38	14/26/38	14/26/38	14/26/38	14/26/38
<b>Welded in brackets = special execution</b>					



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**Overview and Technical Data:**

# **STARRAG HECKERT - CWK 400 D with palett changer + aluminium option**

## **STARRAG HECKERT**



Starrag Group

Year of Build:  
May 1999

## **Description:**

# **Used STARRAG HECKERT FCWK 400D Dynamic 6-station pallet pool, 240 Tower magazine with aluminum finish**

- New spindle at 16 116 hours
- About. 33 568 operating hours
- CNC control Siemens 840 D
- Travel:
  - Column longitudinal travel X-axis 650 mm
  - Support vertical travel 650 mm Y-axis
  - Table traverse Z-axis 650 mm
  - B-axis 360 degrees x 0.001 indexing
  - Rapid traverse 40 m / min.
- Pallet size 400 x 400 mm
- Max Belastung 400 kp
- Drilling / tool spindle speed of 50 to max.15.000 r / min
- Drive power 31 KW
- Tool holder HSK 63
- Dynamic range change in 8 to 9 s by hydraulic rotary changer
- Coolant system
- Dimensions approximately 5.4 x 2.87 x 4.23 m

The motor spindles and speeds of 15 000 rev / min are creating the ideal conditions for the light metal processing, without compromising the high static and dynamic stiffness of the cast iron and steel processing.

The CWK 400 D Dynamic reach peak values?: Eilgangwerte to 100 m / min and accelerations up to 15 m/s<sup>2</sup>.

Innovative ideas also stuck in tool handling with the proven tower magazines with 240 tools. Attending dynamics is called for: in 1.5 s is provided the next tool, to 3.5 s to 4 s, the chip-to-chip time is reduced.

Compact in design, space-saving features of the circular memory 6 presets and 1 clamping space. It is powered by an AC servo motor.

For more details see PDFs

## **Technical Data:**

### **Technical Data:**

Control:

[SINUMERIK 840D](#)

Machine Hours:

33.568 hrs.

Spindle Hours:  
16.116 hrs.  
Spindle Speed:  
15.000 rpm  
Tool Capacity:  
240 x

### **Travels:**

X-Axis:  
650 mm  
Y-Axis:  
650mm  
Z-Axis:  
650 mm

### **Dimensions and Weight:**

Height:  
2.870 mm  
Width:  
4.230 mm  
Length:  
5.400 mm  
Weight:  
12.800 kg

### **Buyer Information:**

Condition:  
Very good condition  
Availability:  
Sold  
Sold as:  
EXW (Ex Works - Incoterm)  
VAT:  
19 %  
Location:  
Germany



1



2





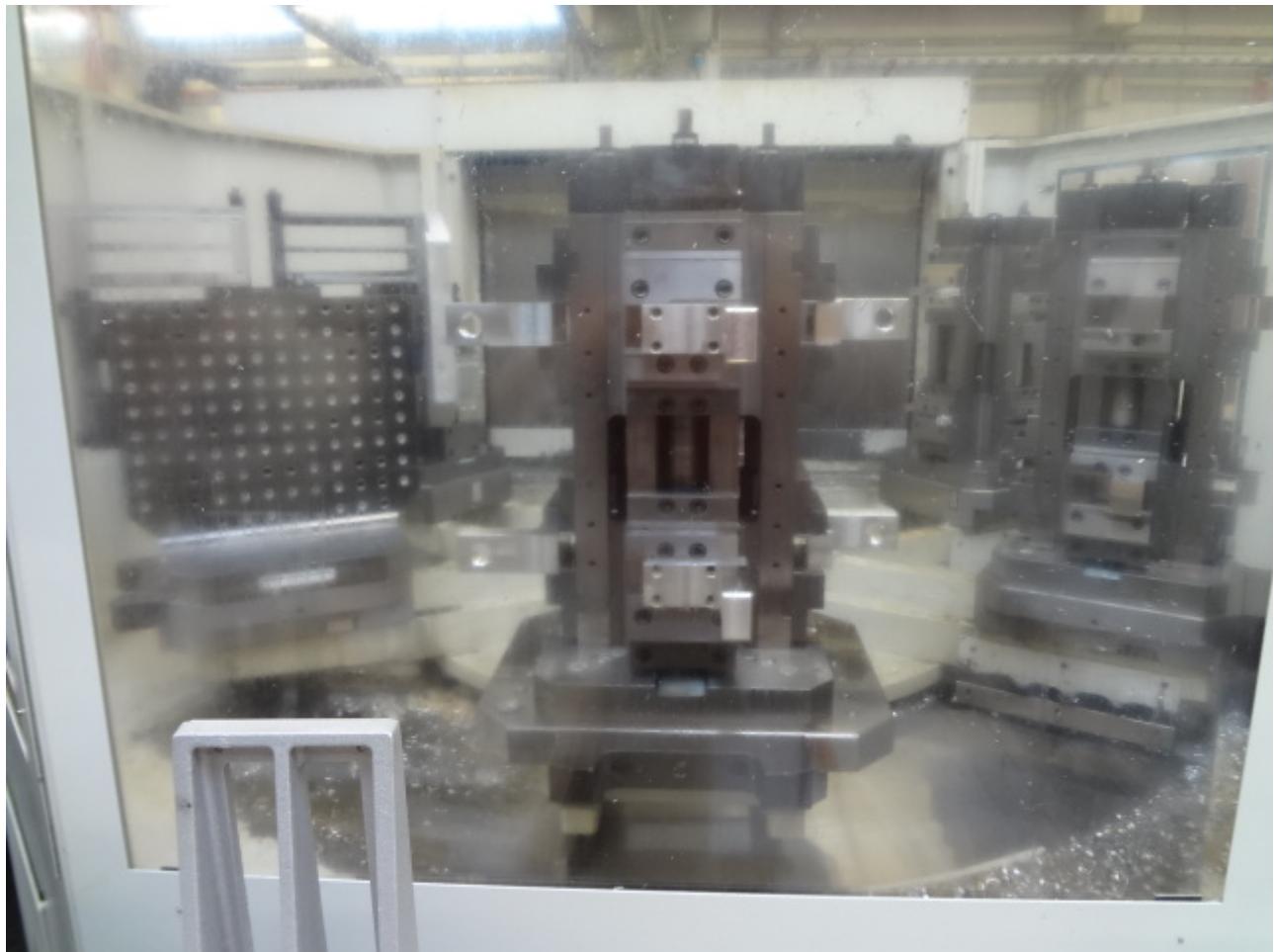
3



4







7



8







11



12









16





**heckert**

starrag-heckert group

Heckert Werkzeugmaschinen GmbH  
D-09117 Chemnitz Otto-Schmerbach-Str. 15-17

Typ	<b>CWK 400 D</b>
Maschinen - Nr.	<b>18272</b>
Baujahr	<b>1999</b>
Temperaturbereich	<b>+5...35 °C</b>
Gesamtmasse	<b>12,5 t</b>



Made in Germany



SIEMENS

Intervall  
speicher  
Kanal aktiv  
Programm läuft  
510220 : Einlesespur bei Werkzeugwechsel

Speicherabbild





Benennung	Einheit	Wert:	Option
		CWK 400D	
		CWK500D	
<b>Positionsgenauigkeiten in den Achsen X, Y, Z nach VDI / DGQ 3441</b>			
Normalausführung	Positionierunsicherheit $P(T_3)$	µm	9
	Positionsabweichung $P_s$	µm	8
	Positionsstreubreite $P_{\text{streu}}$	µm	7
	max. Umkehrspanne $U_{\text{max}}$	µm	6
Hochgenauigkeits- ausführung	Positionierunsicherheit $P(T_3)$	µm	6
	Positionsabweichung $P_s$	µm	5
	Positionsstreubreite $P_{\text{streu}}$	µm	4
	max. Umkehrspanne $U_{\text{max}}$	µm	3

Benennung	Einheit	Wert	Option
		CWK 400D	
		CWK500D	
<b>Betreiberbedingungen</b>			
<b>Elektrotechnische Anschlußwerte</b>			
Werte sind ausstattungsabhängig / detaillierte, maschinengebundene Angaben: Installationsplan (Teil Transport/Aufstellung/Inbetriebnahme)			
Netz	V	400 <small>10%</small>	
Betriebsspannung	Hz	50 <small>±1%</small>	
Frequenz	kVA	75	
Anschlußwert			
bei Normalausführung (Hauptantriebs-Leistung 24 kW)			
bei Ausführung mit erhöhter Beschleunigung	kVA	100	•
Dauerleistungsbedarf	kW	65	
bei Normalausführung (Hauptantriebs-Leistung 24 kW)			
bei Ausführung mit erhöhter Beschleunigung	kW	87	•
Steuerspannung	DC/Gleichstrom	V	24
<b>Umgebungsbedingungen</b>			
Temperaturbereiche	°C	+10 bis +35	
für Funktionsfähigkeit	°C	+20 <small>±2</small>	
für Nenngenauigkeit (Normalausführung)	°C	+20 <small>±1</small>	
für Nenngenauigkeit (Hochgenauigkeitsausführung)	°C	+20 <small>±1</small>	
zulässige Temperaturänderung	°C / Stunde	0,5	
zulässige relative Luftfeuchte	bei 20 °C	%	max. 80
zulässige Luftverunreinigung			es gelten die Werte der elektrotechnischen Ausrüstung
	Niederschlag (30d)	g/m <sup>2</sup>	1
	wasserlöslicher Staub	mg/m <sup>3</sup>	0,2
<b>Druckluftanschluß / Pneumatik</b>			
Anschlußdruck	bar	6,1 bis 10	
Luftverbrauch	kurzzeitiger Spitzenverbrauch	m <sup>3</sup> / min	3,5
	Mittelwert bei Normaldruck	m <sup>3</sup> / Stunde	9
Restölgehalt	mg / m <sup>3</sup>		≤0,1
Restfeuchte	g / m <sup>3</sup>		≤2,75
Verunreinigung	Teilchengröße	µm	≤1
	Massenkonzentration	mg / m <sup>3</sup>	≤5

Benennung	Einheit	Wert	Option
		CWK400D	CWK500D
Sinumerik 840 D			
<b>Steuerung</b>			
<b>Massen / Raumbedarf</b>			
Anhängemasse	Maschine	kg	ca. 12.800 ca. 15.000
Länge	Normalausführung ca.	mm	4.600 4.850
Breite	Normalausführung ca.	mm	3.920 4.000
Maschinenhöhe (bei Kettenmagazin)	über Unterkante Bett	mm	2.900 2.950
Maschinenhöhe (bei Turmmagazin)	über Unterkante Bett	mm	2.700 2.950
Montagehöhe	über Unterkante Bett	mm	3150 3300
Höhe Unterkante Bett über Fußboden	Normalausführung ca.	mm	125
<b>Lärmemission</b>			
Lärmpegel	dBA	< 76 Prüfbedingungen: 1,6 m; Hauptgetriebe $n_{max}$ links und rechts; mittlerer Vorschub in allen Achsen nacheinan- der; Arbeitsraumschutz geschlossen, Mes- sung vor dem Spannplatz und am Einlegeplatz; Meß- gerät: Schallpegelmesser	

Benennung	Einheit	Wert	Option
		CWK 400D	CWK500D
<b>Hydraulik</b>			
Pumpe	Druck Förderstrom	bar l/min	85 bis 90 22,5
Ölbehälter	Ölmenge	l	40
Antriebsmotor	Leistung	kW	4
	Anzahl der Kreisläufe	-	1
<b>Späneförderer</b>		mm	450
Nutzbreite	Standardausführung	mm	1050
Abwurfhöhe			
<b>Kühlaggregat</b>			
Kältemittel	Inhalt	-	R 134 A
Wasserbehälter		l	ca. 30
Zusatz gegen Korrosion		-	10% Anticorit

Benennung	Einheit	Wert	Option
			CWK 400D CWK500D
<b>Prozessschmierung</b>			
Anzahl der Kreisläufe	-	2	
<b>durch Spindelmitte</b>			
manuell schaltbar	l/min	30/27/24	•
	bar	30/40/50	•
schaltbar mit M-Befehl	l/min	30/27/24	•
	bar	30/40/50	•
über Düsen	l/min	50	
	bar	2	
<b>Schwalldusche</b>			
	l/min	ca. 70	•
Anzahl der Düsen am Dach	-	4	•
<b>Spülpistole</b>			
am Spannplatz	-		
Filterart	l	900	
mit	l	1350	•
Behälterinhalt	l	1250	•

Benennung	Einheit	Wert		Option
		CWK	400D 500D	
<b>Werkzeug-Kettenmagazin</b>				
Span-zu-Span-Zeit (gemessen nach VDI 2452)	s	5 **	6 **	
	s	4 **	5 **	•
	s	3,5 **	--	•
			60	
<b>Anzahl der Werkzeugplätze</b>				
max. Werkzeugdurchmesser	bei freien Nachbarplätzen	mm	Ø 160 *	
	bei belegten Nachbarplätzen	mm	Ø 85	
	bei freien Nachbarplätzen und Arbeitsspindel-Drehzahl erhöhung 24000 Upm	mm	Ø 125	•
max. Werkzeugauskraglänge		mm	350 *	400 *
max. Werkzeugmasse	bei Arbeitsspindel-Drehzahl erhöhung 24000 Upm	kg	10	
		kg	5	•
max. Kippmoment	(an Griffstelle des Basishalters)	Nm	10	
Gesamtmasse	aller Werkzeuge im Speicher	kg	200	
max Unwucht	der Werkzeuge bei unsymmetrischer Bestückung	kg	80	
<b>Werkzeug-Turmmagazin</b>				
Span-zu-Span-Zeit	bei Elgang 40 m/min	s	5 **	6 **
	bei Elgang 82 m/min	s	4 **	5 *
<b>Anzahl der Werkzeugplätze</b>				
max. Werkzeugdurchmesser	bei freien Nachbarplätzen	mm	Ø 160	
	bei belegten Nachbarplätzen	mm	Ø 80	
	bei freien Nachbarplätzen und Arbeitsspindel-Drehzahl erhöhung 24000 Upm	mm	Ø 125	
max. Werkzeugauskraglänge		mm	350	
max. Werkzeugmasse	bei Arbeitsspindel-Drehzahl erhöhung 24000 Upm	kg	10	
		kg	5	•
max. Kippmoment	(an Griffstelle des Basishalters)	Nm	10	
max. Geschwindigkeit Q-Achse (Quer/Horizontalbewegung)		m/min	100	
max. Geschwindigkeit V-Achse (Vertikalsbewegung)		m/min	70	

- Einschränkungen bei max. Werkzeuglänge in Verbindung mit max. Werkzeugdurchmesser lauf Skizze Pkt 11.2.9.1 beachten!
- Bei Einsatz eines Winkelbohrkopfes und / oder Werkzeugaufnahme SK 40 erhöht sich die Span-zu-Span-Zeit um ca. 0,5 sec.

Bennung	Einheit	Wert	Option	
			CWK	400D 500D
<b>Arbeitsspindel / Hauptmotor</b>				
Durchmesser im vorderen Lager	mm	Ø75		
Werkzeugaufnahme		HSK-A63 DIN 69893		
		SK 40-AD DIN 69871		*
		Anzugsbolzen DIN 69872-19		
<b>Variante</b>				
<b>Motorspindel Starrag und HSK - A63</b>				
Drehzahlbereich	min <sup>-1</sup>	50 ... 15 000		
		40% ED	100% ED	
	kW	31	19	
Motorleistung	Nm	200	165	
Drehmoment				*
<b>Variante</b>				
<b>Motorspindel Starrag und SK 40</b>				
Drehzahlbereich	min <sup>-1</sup>	50 ... 10 000		
		40% ED	100% ED	
	kW	31	19	
Motorleistung	Nm	200	165	
Drehmoment				*
<b>Variante</b>				
<b>Motorspindel Starrag und HSK - A63</b>				
Drehzahlbereich	min <sup>-1</sup>	50 ... 10 000		
		40% ED	100% ED	
	kW	31	19	
Motorleistung	Nm	200	165	
Drehmoment				*
<b>Variante Hohlwellenmotor und SK 40</b>				
Drehzahlbereich	min <sup>-1</sup>	50 ... 10 000		
		40% ED	100% ED	
	kW	37	24	
Motorleistung	Nm	350	230	
Drehmoment				

Benennung	Einheit	Wert		Option
		CWK	400D 500D	
<b>Verstellwege</b>				
X - Achse (Ständerverstellung)	mm	650	750	
Y - Achse (Support-Senkrechtnverstellung)	mm	650	750	
Z - Achse (Tisch-Querverstellung)	mm	650	700	
<b>Verfahrbereich</b>				
min. Abstand Spindelvorderkante - Mitte Werkstückträger	mm	50	100	
min. Abstand Spindelmitte - Oberkante Werkstückträger	mm	30	80	
<b>lineare Vorschubachsen X / Y / Z</b>				
Vorschub	mm/min	0 ... 40 000 0 ... 82 000 0 ... 100 000		•
Eilgang	m/min	40		
	m/min	82		•
	m/min	100		•
technologisch verwertbare Vorschubkraft	60% ED	kN	12*	
	100% ED	kN	10*	
Meßsysteme:				
linear, optisch-inkremental, abstandscodiert				
Genauigkeitsklasse	µm	±5		
Teilungsperiode der Strichgitterteilung	µm	20		
Eingabe- und Anzeigefeinheit	µm	1		
Beschleunigung X/Y/Z	bei Eilgang 40m/min	m/s <sup>2</sup>	7	
	Eilgang 82m/min bei Hohlwellenantrieb	m/s <sup>2</sup>	9,3 / 9,6 / 10	•
	bei Motorspindel	m/s <sup>2</sup>	4 / 5,5 / 4,5	•
	Eilgang 100m/min	m/s <sup>2</sup>	15/15/12	•

\* Beachten Sie die Einschränkung der Vorschubkraft  
(siehe Bild 1: Diagramm Zulässige Vorschubkraft im oberen Y-Bereich)

Benennung	Einheit	Wert:		Option
		CWK	400D 500D	
<b>NC-Drehtisch / Drehachse B</b>				
max. Drehzahl	min <sup>-1</sup>	25		
Eingabe- und Anzeigefeinheit	Grad	0,001		
zul. Tangentialmoment (Tisch geklemmt)	Nm	3000		
zul. Tangentialmoment bei Dreharbeiten	Nm	530 bei 100% ED 1000 bei 60% ED		
max. Kippmoment ab Oberkante Palette	Nm	5000		
Positionierzeiten	s	0,8		
45°	s	1,2		
90°	s	2,0		
180°	s	12"		
Normalausführung	Positionunsicherheit P (T <sub>p</sub> )	10"		
max. Positionsstreuubreite P <sub>max</sub>		6"		
max. Umkehrspanne U <sub>max</sub>		6"	•	
Hochgenauigkeitsausführung	Positionierunsicherheit P (T <sub>p</sub> )	5"	•	
max. Positionsstreuubreite P <sub>max</sub>		3"	•	
max. Umkehrspanne U <sub>max</sub>				

11.5 Technische Daten

Benennung	Einheit	Wert		Option
		CWK	400D	
<b>Palette</b> (am Spannplatz drehbar)				
Aufspannfläche	mm x mm	400 x 400 400 x 500	- -	•
	mm x mm	-	500 x 500 500 x 630	•
max. Belademasse pro Palette (mittig)	kg	400	500	
bei Elgang 82 m/min	kg	300		•
bei Elgang 100 m/min	kg	200		•
zul. Moment bei außermittiger Last	Nm	200		
Höhe der Werkstück-Aufspannfläche über Unterkante Bett (Spannplatz)	mm	1000		
Richtbohrung - Durchmesser	mm	$\varnothing 20$ H 6		
Abstand zur Tischmitte	mm	150 $\varnothing 0,013$	200 $\varnothing 0,013$	
Aufnahmebohrung ohne Spannhydraulik in Verbindung mit Spannhydraulik	mm	$\varnothing 50$ H 6 $\varnothing 20$ H 6		
Befestigungsgewinde (Normalausführung)		43 x M12	23 x M12	
T-Nut (ähnlich DIN 650)	mm	14		
Werkstück-Durchlaßhöhe	mm	750	900	•
max. Störkreis	mm	$\varnothing 700$	$\varnothing 800$	
Spannhydraulik für Werkstückspannung		3 Anschlüsse		•
<b>Automatischer Palettenwechsel</b>				
Anzahl der wechselbaren Paletten	-	2		
max. Palettenwechselzeit bei Normalausführung	s	8	9	
bei Ausführung mit Spannhydraulik mindestens	s	10		

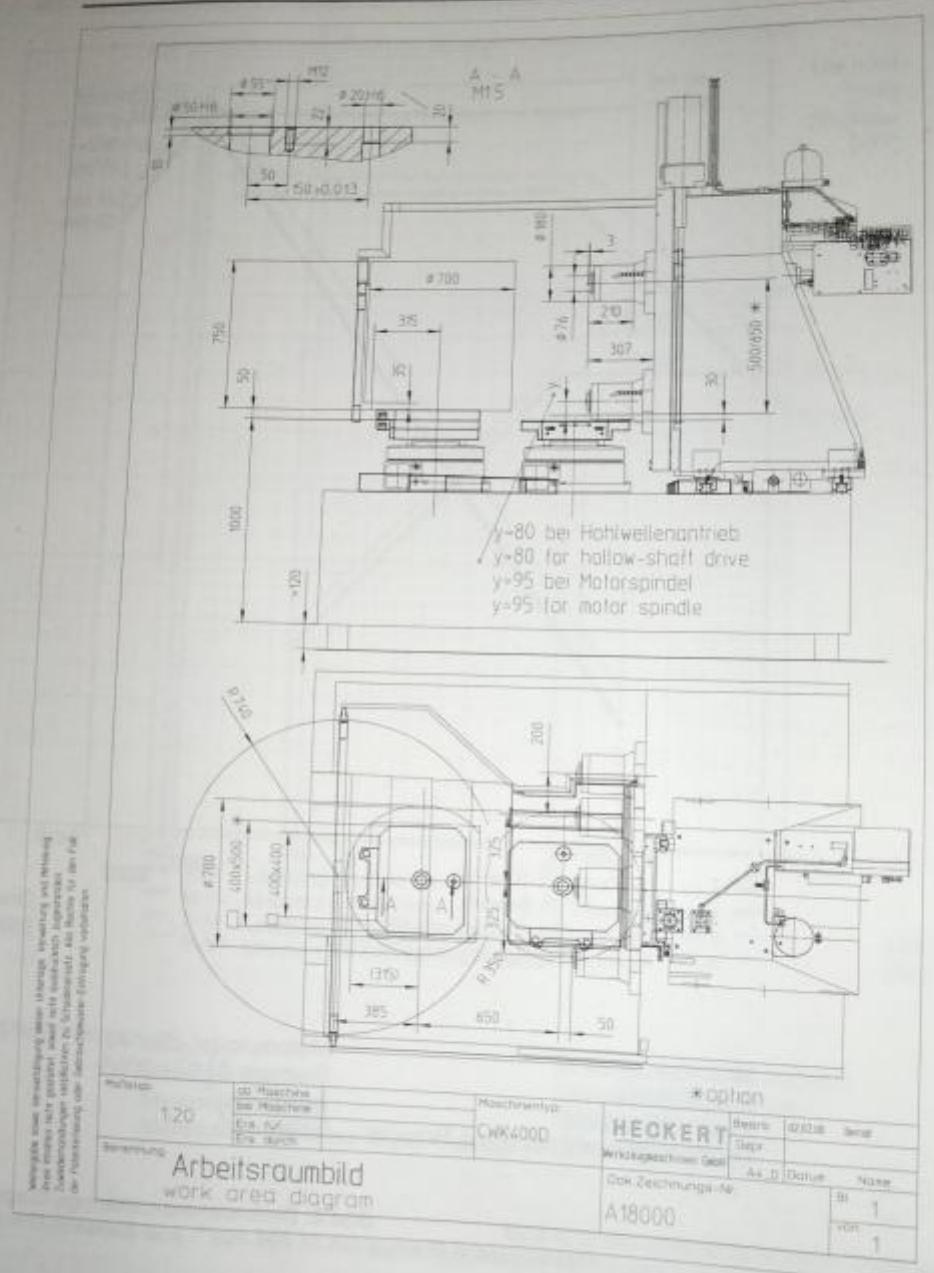
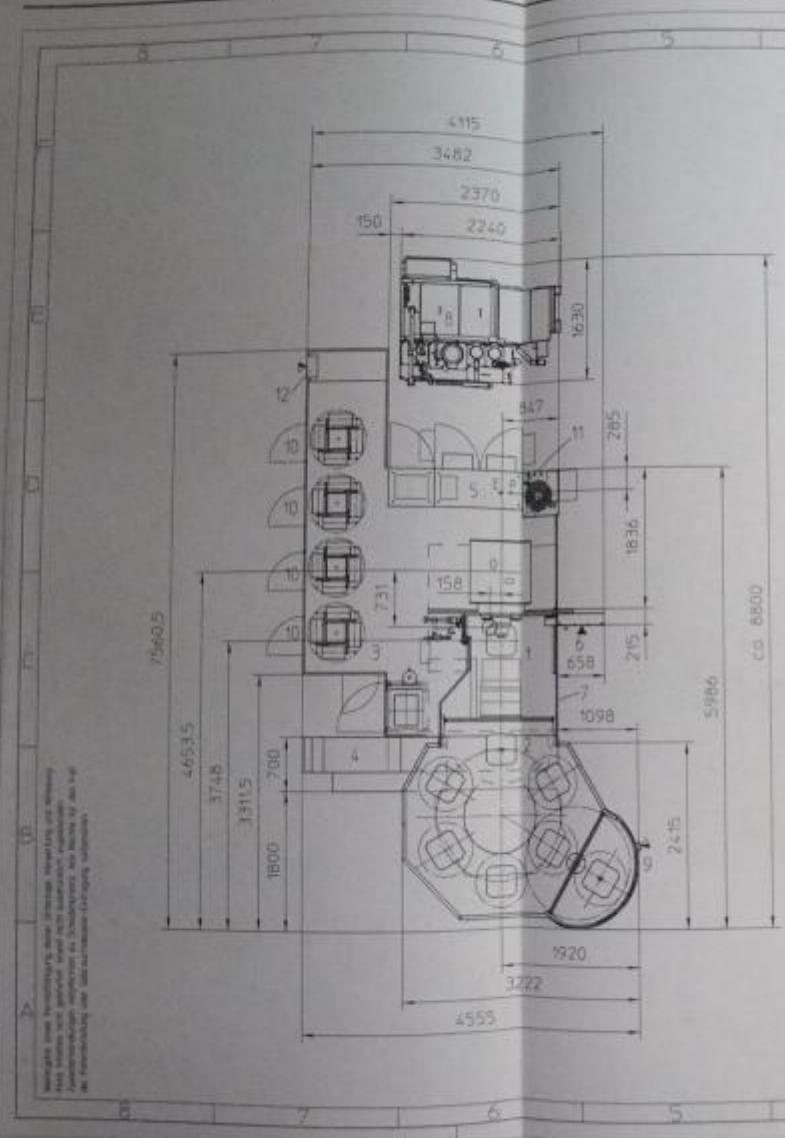


Bild 6: Arbeitsraumbild

1840g 07.9.2001

Betriebsanleitung



18409 07 9 2001

Betriebsanleitung

D 259 von 259

## Transport/Aufstellung/Inbetriebnahme Abschnitt 5

HECKERT  
CWK400D /500D

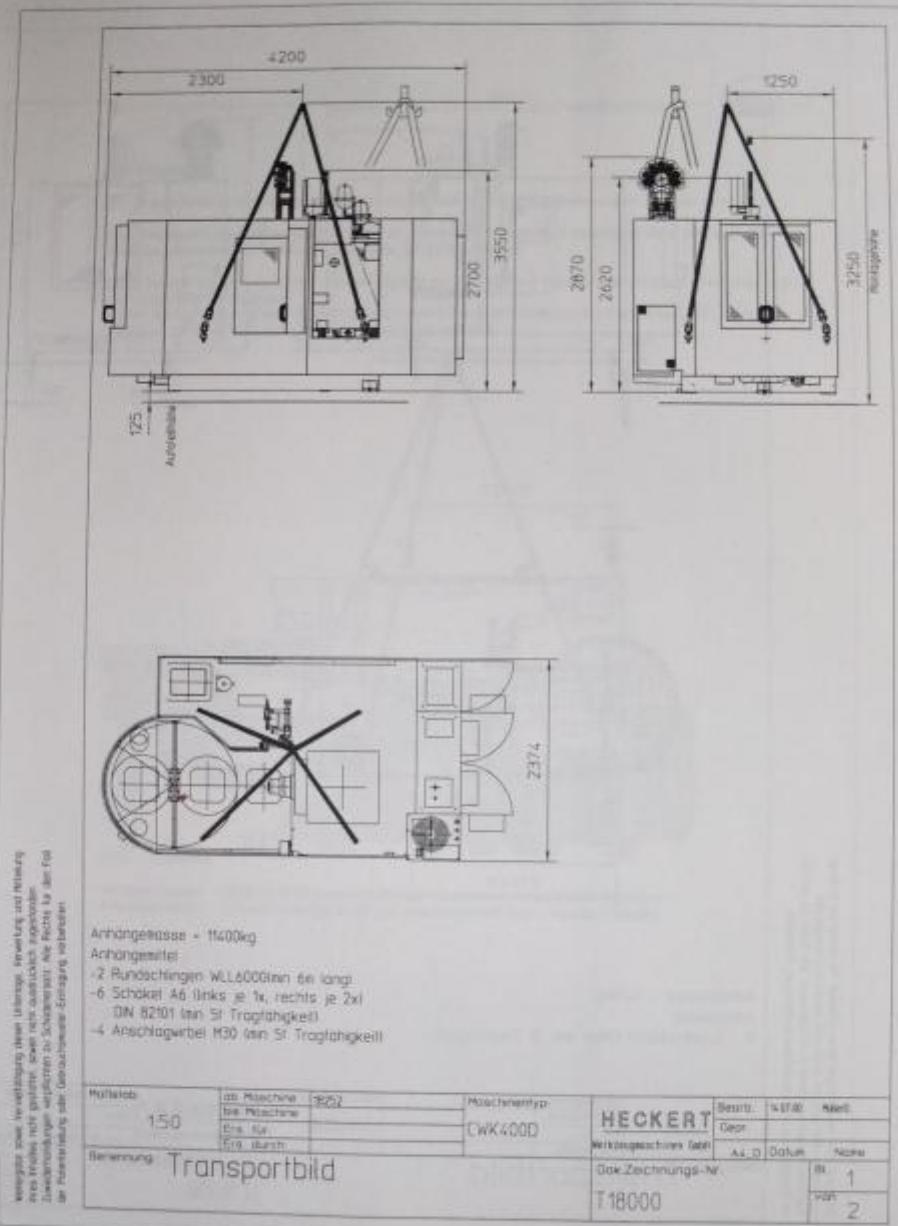


Bild 6: Transport Maschine Bl. 1

18409 16.08.2001

Betriebsanleitung

27 May 30

34

### Transport/Aufstellung/Inbetriebnahme Abschnitt 5

HECKERT  
CWK400D / 500D

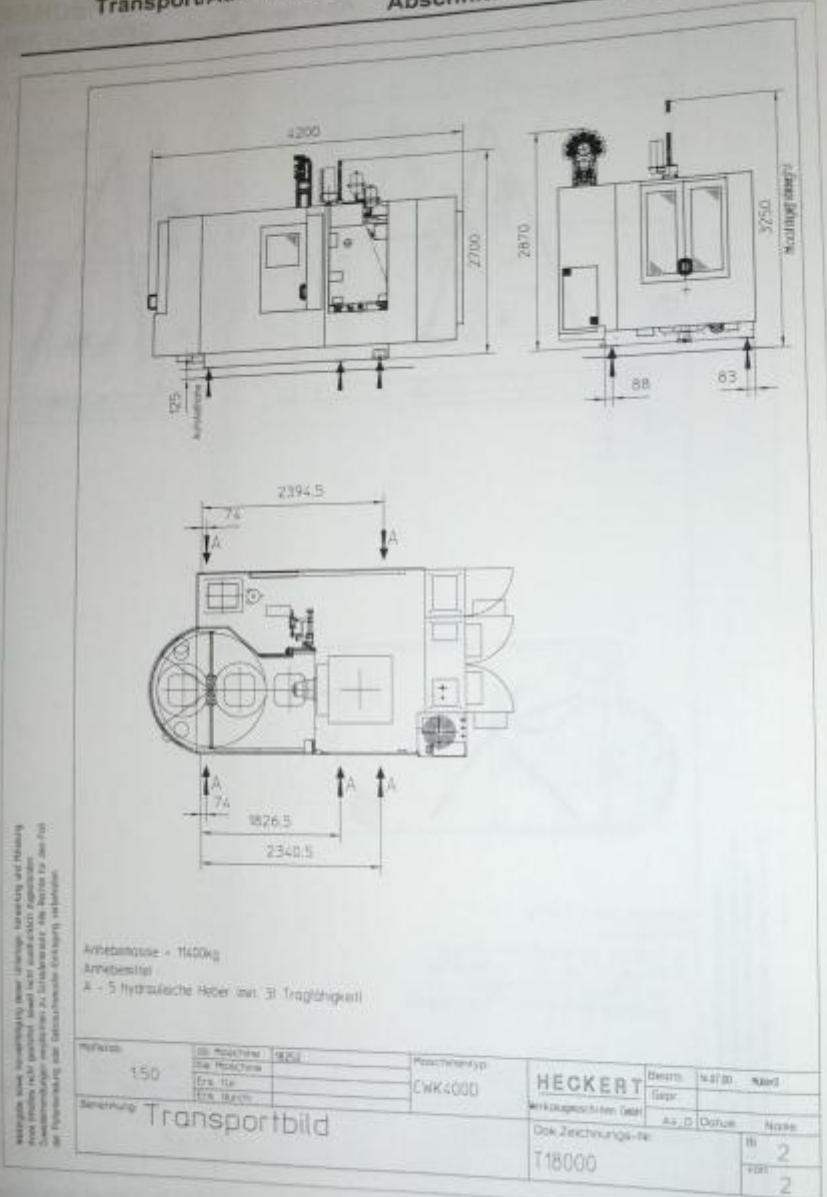


Bild 7: Transport Maschine

18409 16.08.2001

## Betriebsanleitung

D 28 - 28



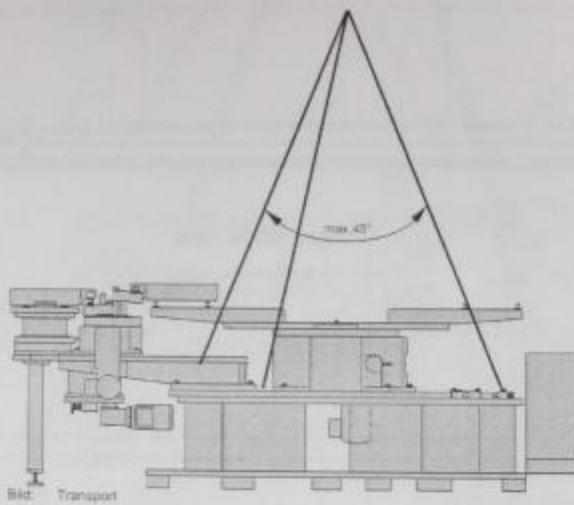
## 2. Transport

Der Palettenpool ist eine kompakte Baugruppe die nach der Inbetriebnahme in dem Zustand verbleibt.

Das Anhängen des Palettenpool darf nur an den mitgelieferten M20 Anschlagwirbel erfolgen. Das Einsetzen anderer Anhängeschrauben ist nicht zulässig!

Die 6 Schrauben zwischen Verschiebeplatte und Grundkörper müssen beim Transport fest angezogen sein (siehe Bild Grundgestell).

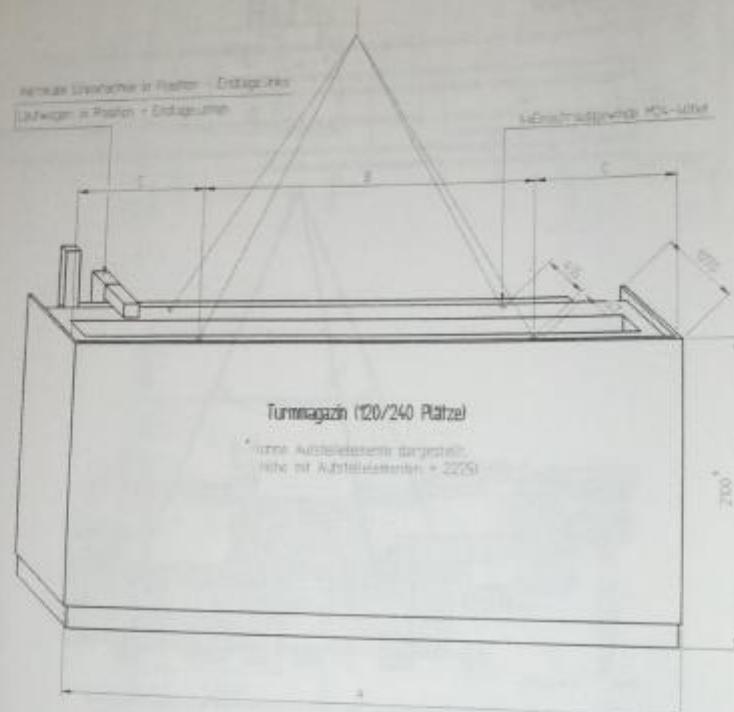
Halten Sie die einschlägigen Unfallverhütungsvorschriften beim Transport des Palettenpool ein, die unter anderem den Aufenthalt unter schiebenden Lasten verbietet.



Anhängemasse: 3800 kg (Palettenpool komplett mit elektromechanischen Wechsler)  
Anhängemitte: 3 Anschlagwirbel M 20 (pro Anschlagwirbel sind 2 Tonnen zulässig)

Bild 8: Transport Palettenpool

Anhängerbild-Krantransport



Turmmagazin-Typ	A mm	B mm	C mm	Masse kg
240 Plätze	4250	2906	372	1260
120 Plätze	2970	965	372	2780

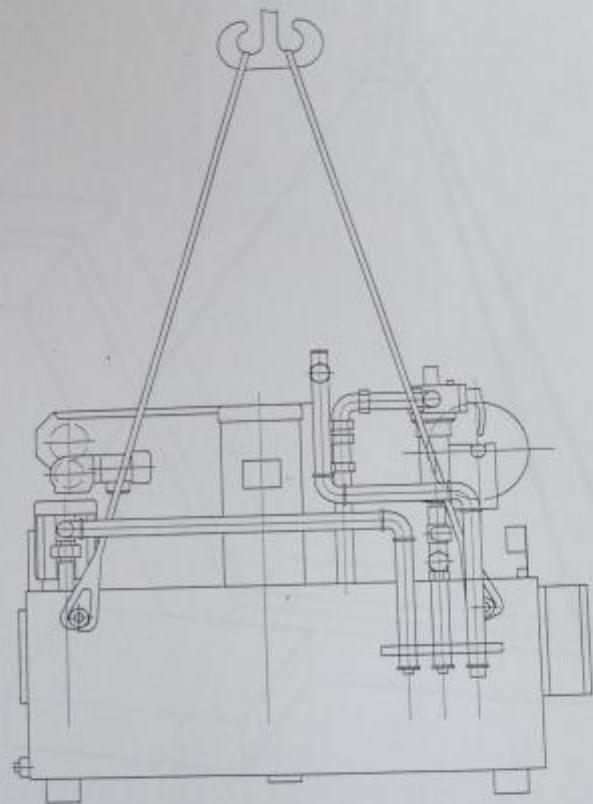
Bild 9: Transport Turmmagazin

18409 16.08.2001

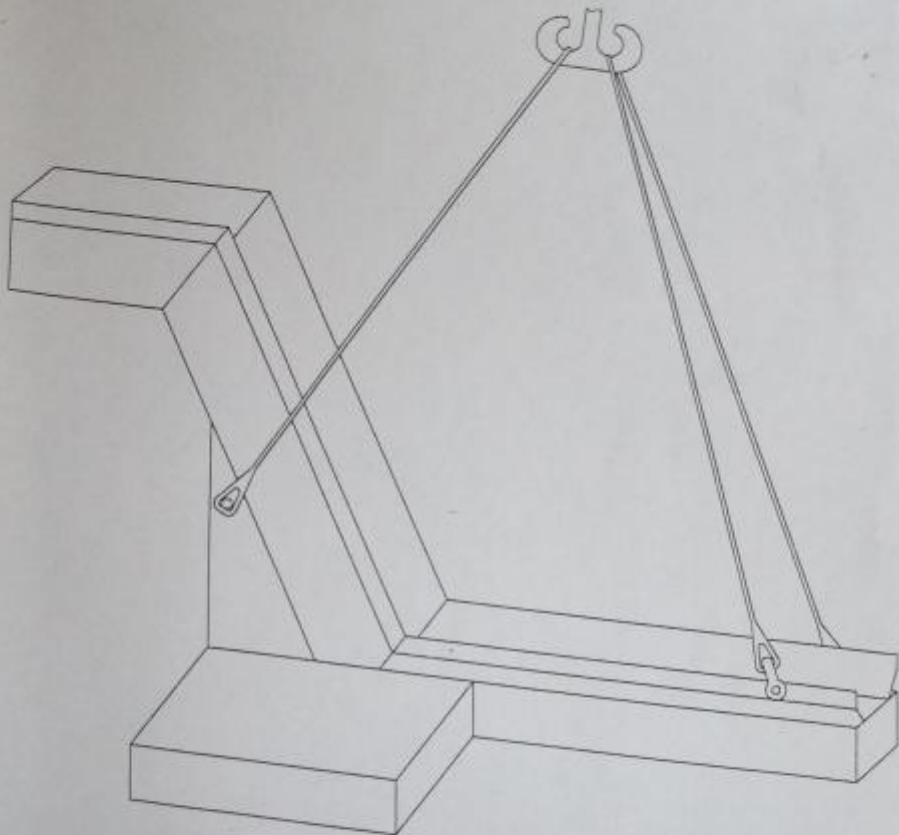
Betriebsanleitung

D

30 von 30



Projekt-Nr.	ab Maschine	2000	Maschinen-Nr.	Bearb.	70/81/900
120	ab Maschine			Ges.	11
	frs. für				
	frs. durch				
Benennung			Sachnummer	Stk.	7
TRANSPORTBILD, KÜHLMITTELBEHÄLTER			T20000	inh.	9



MaschID 120	Ab Maschine bis Maschine	20001	MaschinenTyp: EWK 1000	HECKERT Unternehmensgruppe Gmbh	Start:	2014-06-10 00:00:00
	Ers für:				End:	11:59:59
	Ers durch:				Status:	Neu
Bemerkung:			Sachgruppe:		Start:	8
TRANSPORTBILD, SPÄNEFÖRDERER				T20000	End:	9

With Ever More  
To The New Mill



The new HECHT CWK 500 D Centres have been developed to meet the demands of more reliable, more effective, using motor speed ranges of 15,000 rpm or more. These conditions have been optimised for metal machining, high static accuracy and machining capacity. The customers' requirements could be reduced to a minimum extent. The CWK 500 D has the highest dynamic performance, achieving top feed rates of up to 1,200 mm/min. Feed rates of up to 1,000 mm/min. The centres are manufactured with 82 innovative ideas, implemented in tooling, the well-proven design with max. 240 mm stroke, developed a new design with 60 pockets and a gap of 10 mm between magazine and tool. This also substantially reduces the sequential tool change time from 1.5 sec. and can be reduced to 3.5 sec.

## All Around A Direct Hit

**1** Installation without any need for foundation

thanks to compact design with T-type bed and columns with reduced mass

**2** Safe and extremely fast part removal

from the working zone thanks to start-bed design, part conveyor arms and part conveyor as preconditions for dry machining

**3** Highest positioning accuracies

$P \pm 0.006$  mm and  $P_{max} \leq 0.004$  mm in all linear axes by means of linear motion guideways

**4** Highest rapid traverse rates and short controller acting times

thanks to digital AC servo drives with pre-loaded ball lead screws

**5** Dynamic package 1 g (optional)

with rapid traverse rate of 82 m/min, acceleration rate of 10 m/s<sup>2</sup> and motor-driven spindle of 15,000 rpm

**6** Dynamic package 1.5 g (optional)

for CWK 400 D) with rapid traverse rate of 100 m/min, acceleration rate of 14 m/s<sup>2</sup> and motor-driven spindle of 15,000 rpm

**7** Main drive

in variants with motor-driven spindle  
- driving power ratings of up to 21 kW, speed range of up to 10,000 rpm, steep-taper tool receptor AD 40 or hollow-shank taper HEK 63

- driving power ratings of up to 31 kW, speed range of up to 15,000 rpm, HEK 63 tool receptor

- driving power ratings of up to 60 kW, speed range of up to 24,000 rpm, HEK 63 tool receptor

or with hollow-shaft-type motor  
- driving power ratings of up to 35 kW, torque up to 335 Nm, speed range of up to 10,000 rpm, steep-taper tool receptor AD 40

**8** Part changeover time 8 to 9 sec. thanks to hydraulic rotary changer

**9** Rotatable clamping station with 4- $180^\circ$  indexing facility for operator friendly workpiece setting work while the machining cycle is running

**10** NC rotary table for multitasking and complete machining to satisfy highest accuracy demands ( $P \leq 8^\circ$ ,  $P_{max} \leq 1^\circ$ ) with coupling unit for hydraulically workholding fixtures

**11** High-performance in-process control and monitoring facilities use of Siemens 840 D CNC continuous-path controller in 32-bit technology or, as an option, Fanuc 16i including comprehensive control and monitoring facilities

**12** Tool handling with chain-type magazine, change-over times 3.5 to 4 sec., parallel tool location between magazine and main spindle, drive by means of AC servo motor to reduce the availability times for segmental tool and the chip-removal times

**13** Tool handling with tool tower magazine

space-saving option with regard to chain-type magazine for increased tool demands of up to 240 pockets with smallest installation area and tool changeover in parallel to production time

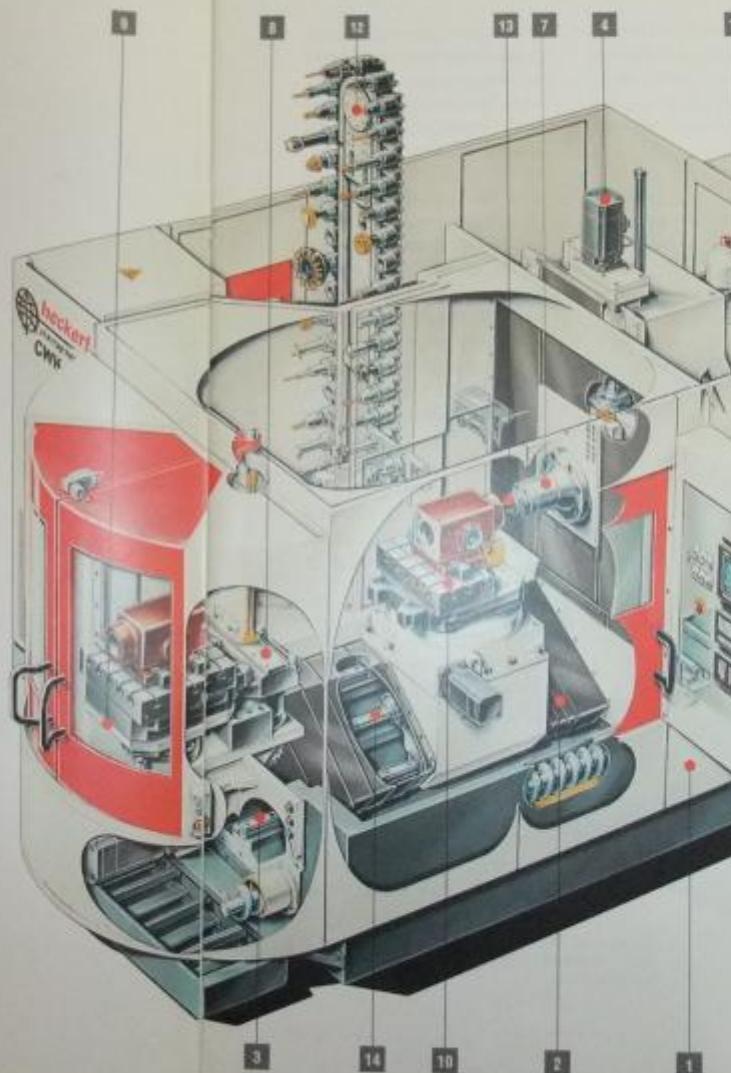
**14** Coolant system

wet machining with constant supply through nozzles or through spindle centre with a delivery pressure rating of up to 50 bar or dry machining with minimum-quantity lubrication

**15** Low-maintenance grease lubrication

for motor-driven spindle, ball lead screws and linear motion guideways

**16** Conversion into manufacturing cells and flexible manufacturing systems with circular and linear magazines for workpiece pallets



## Economy And Ecology Form An Optimal Entity

- The compact design of HECKERT CWK 400 D and CWK 500 D centres with a T-type bed, carrying all major machine elements in the condition for transporting the machine as a single complete entity, for installation without any need for foundations and instant readiness for use. This saves foundation, transportation, and assembly costs and makes sure that tool production can be started even earlier.
- All major machine elements feature excellent shock absorbing qualities and a very limited heat expansion to ensure vibration-free machining with high performance.

■ To ensure fast and safe swarf removal from the working zone, the machine bed has been configured in slant-bed design. The consequential prevention of heat accumulation will create ideal conditions for dry machining.

■ Extremely high running, positioning and permanent accuracies are ensured by optimally dimensioned linear motion guideways in all linear axes.

■ Incremental, direct linear encoder systems with distance coding have been encapsulated in aluminum casings and

are pressurized with compressed air. So, the encoder systems are protected from swarf, coolant and contaminations. An incremental encapsulated angular position encoder system is used for the NC rotary axis.

■ Manufacturing tolerance deviations and temperature fluctuations can be compensated for in conjunction with the CNC controller. In the stage of extension featuring enhanced machining accuracy, a positioning deviation of  $P \leq 0.006$  mm and a positioning variation of  $P_{\text{max}} \leq 0.004$  mm in all linear axes and  $P_{\text{max}} \leq 5^\circ$  in the rotary axis can be achieved. So, accuracies in the IT5/IT6 tolerance class can be obtained at the workpiece.

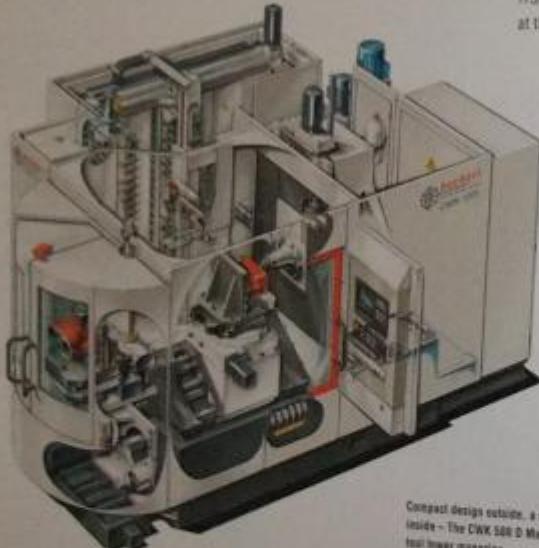
■ The technical concept of the HECKERT CWK 400 D and CWK 500 D consistently applies all necessary considerations for strict adherence to ecological requirements. Total-loss oil lubrication has become a thing of the past. Thanks to grease lubrication for main spindle, ball lead screws and linear motor guideways, maintenance requirements have been reduced quite considerably.

■ With the machine being sealed off the shop floor, any ingress of coolant and hydraulic oil is avoided. This has been achieved by a machine bed which carries all functional machine elements and is hermetically sealed.

■ Faseless coolant purification with vacuum edge strainer and return flow filter for the high-pressure circuit does away with cost-intensive special refuse disposal requirements.

■ In accordance with environment and operator-friendliness, a splash shower in the working zone with a coolant volume rate of 70 l/min, an air-blast gun at the clamping station for cleaning of workpiece and fixture and an emission extraction can be incorporated in the machining centres.

■ A clear view of the working zone is always ensured by a pneumatically operated, rotating inspection window in the working-zone safety door.



Compact Design outside, a variety of innovations inside - The CWK 500 D Machining Centre with four tower magazine

## ■ How A Reduction In Idle Times Can Be All Important



HECKERT CWK 400 D and CWK 500 D Machining Centres  
After heat treatment for light-metal machining of engine components

Optimal cutting conditions with coolant supply  
through spindle centre and through external nozzle



### ■ Main drive

A characteristic of the new HECKERT CWK 400 D and CWK 500 D Machining Centres is the highly dynamic behaviour of the main drive. With a mass-reduced and grease-lubricated motor-driven spindle, speeds of up to 10,000 rpm, 15,000 rpm and 24,000 rpm at power ratings of 31 kW can be reached optionally.

Even for heavy-duty cutting work, HECKERT offers another solution. A hollow shaft-type motor ensures power ratings of 35 kW at torques of 335 Nm.

Optimal conditions are obtained for wet machining. Coolant supply is optionally possible through external, adjustable ball nozzles or through spindle and tool centre. Absolute swarf removal is guaranteed during core drilling with a delivery pressure rate of up to 50 bar. Ideal machining results are achieved in dry machining thanks to the minimum-quantity lubrication.

Clamping and unclamping of tools with steep-taper receptor 40 or hollow-shaft taper HSK-63 function quickly and safely by means of Belleville spring pack and hydraulic cylinder. Blasting of spindle taper and internal coolant supply of tools with compressed air during the automatic tool changeover cycle avoids contamination and prevents negative influences on the machining quality.

### ■ Feed drive

Digital AC servo motors in combination with preloaded ball lead screws ensure short positioning times, minimized controller acting times, maximum rapid traverse rates, and a high stability over the whole range of feed rates. They feature the cost-saving option to the linear drives and reduce idle times above average with rapid traverse rates optionally from 40 mm/min up to 100 mm/min and acceleration rates of up to 15 m/s<sup>2</sup>. Such problems of linear drives as mastering of magnetic forces, expensive cooling and mass-dependent power capacity are excluded when using the rotary HECKERT drives.

Even more dynamics can be achieved by the optionals:

#### Dynamic package 1 g

(CWK 400 D and CWK 500 D)

- rapid traverse rate 82 mm/min
- acceleration rate 10 m/s<sup>2</sup> in all linear axes
- motor-driven spindle with max. 15,000 rpm
- hollow-shank taper HSK-A63
- chip-to-chip time 4 sec.

#### Dynamic package 1.5 g (CWK 400 D)

- rapid traverse rate 100 mm/min

- acceleration rate of up to 15 m/s<sup>2</sup>
- motor-driven spindle with max. 15,000 rpm
- hollow-shank taper HSK-A63
- chip-to-chip time 3.5 sec.

### ■ Pallet changeover

Pallet changeover too is safe, comfortable and ultra-fast. A hydraulically operated rotary pallet changer ensures exchange

of pallets within a time of 10 seconds. Workpieces are clamped in the clamping station and unclamped at the clamping station. The pallet changeover takes place in the standard design of the machine with its 4 × 90° indexing table. An NC rotary table is of course available for machining operations. The table is fitted with a high-pressure system to ensure a positioning dynamics and a position accuracy that satisfy highest quality requirements. The NC rotary table is available with a coupling and a high-pressure stage to support the holding fixtures.



## Highest Innovation During Tool Changeover

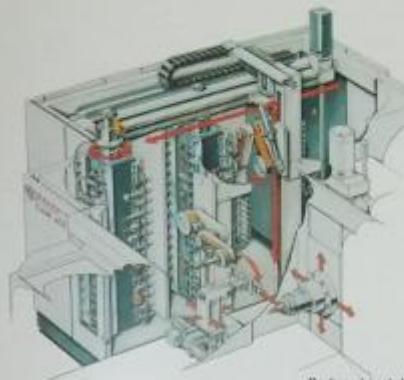
The tool handling is optimally matched with the machining job. Whether equipped with chain-type magazines for 80 tools or with tool tower magazine for 120 or 240 tools, the chip-to-chip time with dynamic package is only 3.5 to 4 sec. for tools of 10 kg in weight, 160 mm in diameter and up to 400 mm in length. The chip gripper is located outside the machining area and therefore not subject to coolant and swarf ingress. The enhanced peripheral speed of crane-type magazine will reduce the availability time of unpassive tool to 1.5 sec. This is of particular importance for light-metal machining.

The tool tower magazine, featuring highest tool density at minimum space requirements, reduces setup times, optimizes sequences of operation and enhances operator comfort.

Arrangement of tools in share-type magazine  
is parallel to the main spindle  
ensures a chip-to-chip time of 2.3 sec.



## Advantages of tools as against chain-type magazines



Dynamic tool changeover  
between main spindles and  
tool tower magazine

Reduced installation space

– Highest tool density at  
0.25 m<sup>2</sup> installation space

– Full occupation of space  
without vacant positions

Reduced setup times

– Manual tool changeover  
from magazine during  
within the automatic cycle

– Each tool can be  
located in any position

– Full occupation of  
space without adjacent

Tool tower magazine for  
max. 120 or 240 tools with highest tool  
density at minimum space  
requirements



## Flexible Manufacture Can Be Extended

### ■ Linear magazine

A track-bound workpiece pallet transporter, clamping station for setup work, storage locations in linear arrangement for intermediate storage of workpiece pallets and a cell controller are included in the linear magazine.

The transporter featuring a traverse speed of 60 mm/min as well as short acceleration and deceleration times guarantees short setup times.

The independent NC controller of transporter increases operator comfort and reduces setup expenditure. The transverse conveyor at the transporter ensures double-sided loading and unloading of workpiece pallets and thus a high flexibility in cell structure.

When the storage locations are arranged in 2 or 3 tiers, the transporter simultaneously takes over the function of a pick-and-place device.

Setup work at the clamping station is carried out quickly, safely and under good ergonomic conditions. For clamping, positioning and unclamping of workpieces, for resetting the fixtures and for simple measuring operations, the clamping station can be rotated and indexed  $4 \times 90^\circ$ .

A protection device designed as lifting cage with electric drive and locking functions will increase labour safety and ease of operation.

The storage locations guarantee limited operator attendance for intermediate and buffer storage and can be arranged in one tier or in 2 or 3 tiers to save space.

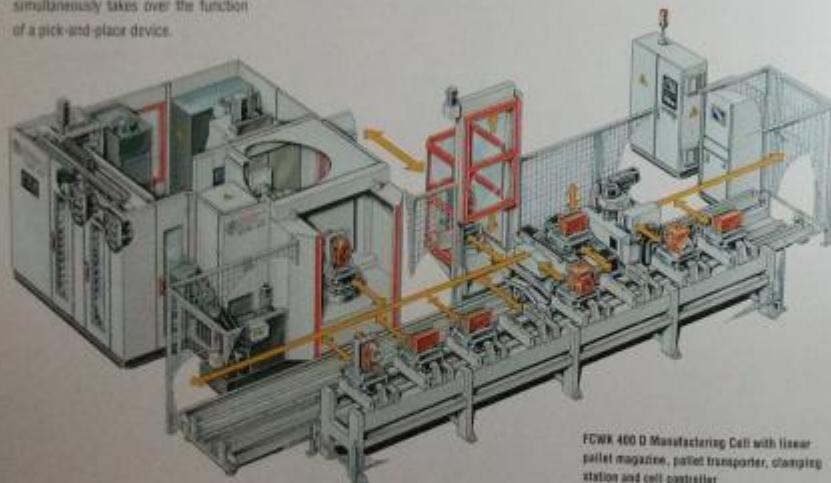
### ■ Circular magazine

The circular magazine in compact and, thus, space-saving design has got 6 storage locations and 1 clamping location and is driven by means of an AC servo motor.

To ease operation, the incorporated clamping station can be rotated and indexed for workpiece setup work.

The workpiece pallets are quickly and safely transported from the clamping station to the circular magazine according to the rotary-changer principle.

Following the same principle, the pallets

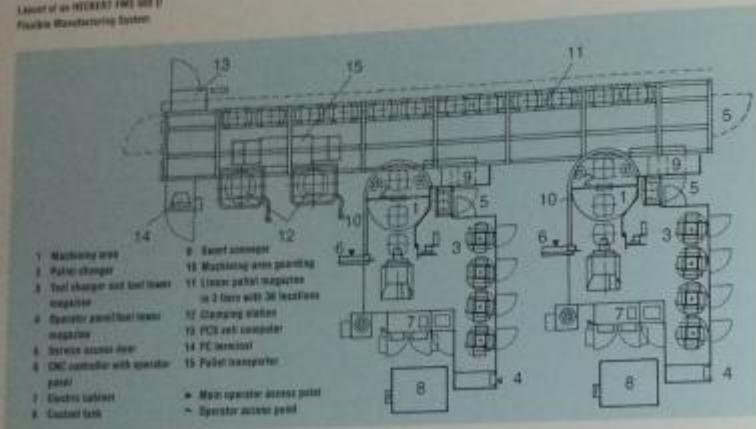


FCWK 400 D Manufacturing Cell with linear pallet magazine, pallet transporter, clamping station and cell controller



## Machining Area

Layout of an HECKERT CWK 400 D  
Flexible Manufacturing System



### Control and monitoring facilities

Comprehensive control and monitoring facilities are at choice for the HECKERT CWK 400 D and CWK 500 D Machining Centers as a precondition for semi-unattended manufacture and for reducing manual inspection work.

The target value and remaining life expectancy per tool are indicated on the CNC monitor screen for monitoring of

tool lifetime and consequential steps are automatically initiated upon any excess thereof. The main drive power rating is monitored for wear detection at the cutting edges of tool.

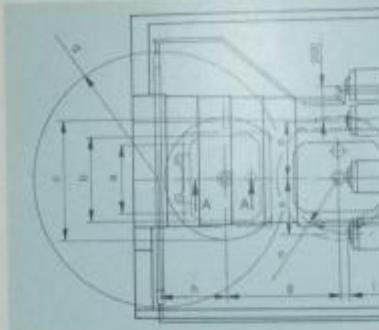
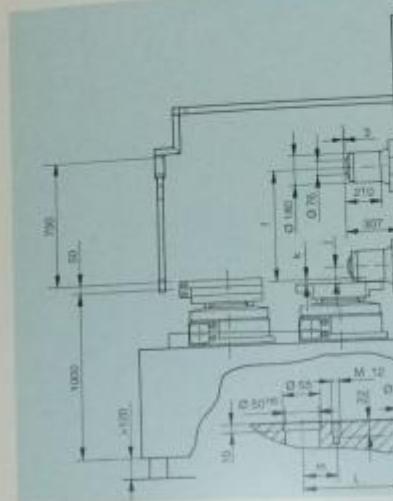
The speed given in the tool list for each tool is permanently monitored to avoid any overspeeding.

Direct tool break monitoring is ensured by means of break detector with pneumatic cylinder.

Direct tool break monitoring  
at break detector



A 3-D measuring probe monitors machining quality and allows for safe and fast zeroing of workpieces, allowance measurements and cut segmentation.



CWK 400 D

a	mm	400 × 400
b (optional)	mm	(500 × 400)
c	mm	700
d	mm	8740
e/ longitudinal travel	mm	× 325
f/ vertical travel	mm	500 (550)
g/ transverse travel	mm	650
h	mm	385
i	mm	50
j	mm	95 for motor-driven spindle (80 for hollow-shaft motor)
k	mm	30
l	mm	150 ± 0.013
m	mm	50
n	mm	8110

Values in brackets = special execution

## Technical Data

	CKW 400 D	CKW 400 D with dynamic package 1g	CKW 400 D with dynamic package 15g	CKW 500 D with dynamic package 1g	CKW 500 D with dynamic package 15g
<b>NC rotary table</b>					
Clamping surface/light pattern (table DIN 35207)	mm	400 = 400 (300 = 400) / 400 = 400 (300 = 400)	400 = 400 (500 = 400)	500 = 500 (630 = 500)	500 = 500 (630 = 500)
Input and display resolution	degrees	0.001	0.001	0.001	0.001
Max. load	kgf	400	300	500	300
Max. speed	rpm	25	25	25	25
Workpiece swing diameter	mm	700	700	700	700
<b>Automatic pallet changer</b>					
Number of changeover pallets		2	2	2	2
Max. pallet changeover time	sec	8	8	8	8
<b>Transverse range</b>					
Source, main (X-axis)	mm	650	650	650	650
Spindle head, vertical/Y-axis	mm	500 (650)	650	650 (750)	650 (750)
Total, transverse (Z-axis)	mm	650	650	700	700
<b>Max. spindle/Motor-driven spindle</b>					
Power rating at 100 % duty cycle	kW	19	19	19	19
Power rating at 40 % duty cycle	kW	31	31	31	31
Torque at 100 % duty cycle	Nm	165	165	185	185
Torque at 40 % duty cycle	Nm	200	200	200	200
Tool recognition		SK 40 DIN 69821	HSK 03	SK 40 DIN 69821	HSK 03
Tool A		HSK 03		HSK 03	
Speed range	rpm	50...10000 (10000)	50...15000	50...15000	50...15000
Diameter of front bearing	mm	70	70	70	70
Increased power (using hollow-shaft motor optional)					
Power rating at 100 % duty cycle	kW	24	24	24	24
Power rating at 40 % duty cycle	kW	35	35	35	35
Torque at 100 % duty cycle	Nm	230	230	230	230
Torque at 40 % duty cycle	Nm	335	335	335	335
High speed package (optional)					
Max. spindle/drive spindle	rpm		24000		24000
<b>Automatic tool changer</b>					
Chain-type magazine					
Magazine pockets		80	60	80	60
Max. tool diameter	mm	160	160	160	160
Max. tool length	mm	350	350	400	400
Max. tool weight	kg	10	10	10	10
Max. off-torque	Nm	10	10	10	10
Max. chip-to-chip time	sec	5	4	3.5	4
Tool tower magazine (optional)					
Magazine pockets		120/240	120/240	120/240	120/240
Other data same as chain-type magazine					
<b>Transverse rates</b>					
Feed rate range, velocity variable	mm/sec	0...40	0...82	0...100	0...40
Right transverse rate	mm/sec	40	82	100	40
Acceleration rate	mm/sec <sup>2</sup>	7	10	15/12 for 2 axes	7
<b>Coolant system</b>					
Supply through spindle centre					
Volume	l/min	24 (30/27/24)	34 (30/27/24)	24 (30/27/24)	24 (30/27/24)
Pressure	bar	10 (30/40/50)	10 (30/40/50)	10 (30/40/50)	10 (30/40/50)
Supply via杂志					
Volume	l/min	50	30	50	50
Pressure	bar	2	2	2	2
Coolant tank capacity	l	550 (900)	350 (900)	550 (900)	350 (900)
<b>Machine accuracy according to VDI/DSG 3441</b>					
Linear axes X, Y and Z					
Positioning deviation P	mm	≤ 0.01 (0.006)	≤ 0.01 (0.006)	≤ 0.01 (0.006)	≤ 0.01 (0.006)
Positioning variation Pmax	mm	≤ 0.037 (0.004)	≤ 0.037 (0.004)	≤ 0.037 (0.004)	≤ 0.037 (0.004)
NC rotary table					
Positioning deviation P	mm	≤ 12 (6)	≤ 12 (6)	≤ 12 (6)	≤ 12 (6)
Positioning variation Pmax	mm	≤ 10 (5)	≤ 10 (5)	≤ 10 (5)	≤ 10 (5)
Net weight	kg	12800	12800	12800	15000
<b>CNC controller type</b>					
Siemens 840 D (Parus 16.4)	Siemens 840 D (Parus 16.4)	Siemens 840 D (Parus 16.4)	Siemens 840 D (Parus 16.4)	Siemens 840 D (Parus 16.4)	Siemens 840 D (Parus 16.4)
<b>Circular magazines (optional)</b>					
Number of storage locations		8	6	6	8
Design of changing stations				rotatable and rotatable 4 × 90°	
Number of pallets in total system, max.		8	8	8	8
<b>Linear magazine (optional)</b>					
NC transporters				track-bound, with transverse conveyor and lifting device	
Transverse speed, approx.	mm/sec	60	60	60	60
Clamping station				rotatable and rotatable 4 × 90°	
Storage locations, optional design		1, 2 or 3 tiers	1, 2 or 3 tiers	1, 2 or 3 tiers	1, 2 or 3 tiers
Number of tiers	12/24/36	12/24/36	12/24/36	12/24/36	12/24/36
Number of pallets in total system, max.	14/26/38	14/26/38	14/26/38	14/26/38	14/26/38
<b>Welded in brackets = special execution</b>					



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