

OPTIV PERFORMANCE 663/664 DUAL Z



Product description

The Optiv Performance 663 / 664 Dual Z combines optical and tactile measurement in one system. The system supports multi-sensor measurements using the Vision sensor, the touch-trigger and scanning probe, the TTL laser (Through-The-Lens) as well as the innovative Chromatic White Light Sensor (CWS). The basic machine with Vision sensor can be expanded with all the available sensors on a modular basis. Measurement software is PC-DMIS.

Fields of application

- · Use on shop floor
- Versatile geometry measurements, GD&T analysis with standard accuracy

Design

- (1) Optical and tactile sensors are assigned to two independent vertical axes. When measuring complex 3D workpieces the positioning of the sensors is easier. Makes it possible to use turn/pivot probes.
- Design principle:
 - » Low-vibration granite construction with a fixed bridge and a moving table
 - » Integrated subframe with optional vibration dampers
 - » Optiv Dual Z design (1) with two vertical axes
- · Guides:
 - » Precision mechanical linear guides on all axes
- - » DC servo motors, power transmission via backlash free circulating ball screws
- Length measuring system:
 - » Incremental optoelectronic length measuring system
 - » Resolution of the scales 5 nm

Measuring range (X x Y x Z1, Z2)

- (2) Vision sensor <--> Touch-probe (see pages 9 and 10)
- (3) 405 mm (16 in.) with the model Optiv Performance 664 Dual Z

Measuring accuracy (4)

- (4) The conditions of acceptance of Hexagon Metrology Vision apply.
- (5) E is valid for a stylus of \emptyset 5 mm, L = 50 mm.
- (6) P and THP are valid for a stylus of \emptyset 5 mm, L = 20 mm.
- L = measurement length in mm

	Vision sensor, touch-probe	Mutual measuring range (2)
Χ	610 mm (24 in.)	495 mm (19 in.)
Υ	610 mm (24 in.)	610 mm (24 in.)
Z1, Z2 ⁽³⁾	305 mm (12 in.) / 405 mm (16 in.)	305 mm (12 in.) / 405 mm (16 in.)

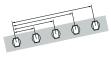
At 20°C, acc. to ISO 10360-7, with Vision sensor, at highest zoom magnification (

Length measuring error

Ex, Ey $= (1.5 + L/250) \mu m$ Еху $= (1.9 + L/250) \mu m$ Ez $= (1.9 + L/250) \mu m$

Probing error

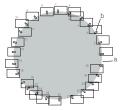
 $= 1.9 \, \mu m$ P_{F2D} $= 1.9 \, \mu m$ P_{FV2D}



Ex, Ey, Exy: On a glass artefact, 5 measurement lengths are measured with 3 repetitions.



axis will be measured on a step gauge block on the basis of 5 measurement lengths with the optical lateral sensor by means of video focus.



a Test circle b Measuring window

The length measurement error Ez for the vertical

P_{F2D} / P_{FV2D}: 25 points are measured, which are equally distributed on a circle. A best-fit circle calculated from these measurements is the basis to determine the range of deviations as a result. The parameter P_{FV2D} is determined at standstill of the CMM, P_{F2D} is determined with movement of the CMM. At 20°C, acc. to ISO 10360-2 / -4, with the HP-S-X1C probing system (4)

Volumetric length measuring error (5)

MPE_E $= (2.9 + L/250) \mu m$

Volumetric probing error (6)

MPE_P $= 2.1 \, \mu m$

Volumetric scanning probing error (6)

 $MPE_{THP} = 2.9 \, \mu m \, (t = 78 \, sec)$



A set of 5 gauges has to be measured 3 times with one probing at each end, in 7 different directions in space. All measuring results must be within "E".



A precision sphere has to be measured with 25 probings. P is the range of all radii.

 $P = R_{max} - R_{min} = sphere form$



A precision sphere has to be scanned with 4 defined lines. THP is the range of all radii.

THP = $R_{max} - R_{min} =$ sphere form, scanning

Loading capacity

Dimensions in mm and weights in kg

Airborne noise emissions

Environmental requirements

Supply data

Throughput

Vision sensor

- · Load-bearing capacity of the glass plate up to 50 kg
- Dimensions see machine layouts on pages 7 and 8
- Machine weight 2100 kg
- The A-weighted emission sound pressure level at operator's position is less than 70 db(A).
- Limits of permissible floor vibration < 5 x 10⁻³ m/s² corresponds to an amplitude of < 5 µm at 5 Hz
- · Air humidity 40 % 70 % RL, non-condensing
- Environmental temperature 20 °C ± 2 °C
- Permissible temperature gradient 0.8 °C/h, 1.0 °C/d, 0.6 °C/m
- Max. installation height 2000 m above sea level
- · Max. traversing speed
 - » 200 mm/s (per axis)
 - » 280 mm/s (in a plane)
 - » 340 mm/s (in space)
- Input voltage power supply 115-230 V ± 10%
- Frequency 50/60 Hz ± 5%
- Power consumption 1000 VA
- Air supply (optional vibration damping system):
 - » Air pressure connection with 1/2-inch quick-connect coupling
 - » Air pressure at least 400000 pascal (Pa), max. 600000 pascal (Pa)
 - » Air consumption approx. 5-20 Nl/min (dynamic), 0.5-1 Nl/min (static)
 - » Pre-cleaned air according to ISO 8573-1 class 1

Technical description

- Sensor for non-contact measurement of smallest and closely toleranced features
 - » High resolution camera, for interference-free, low noise image reproduction
 - » Maximum optical precision due to low distortion optics
 - » Motorised CNC zoom
 - » Optiv Dual Camera
 - » Powerful image processing
 - » Fast, precision video autofocus
 - » Automatic feature detection, geometry and bad pixel video filters
 - » Contour scanning mode:
 - Sophisticated set of user-selectable algorithms to setup edge detection, intelligent, automatic selection of the most suitable setting for the measurement.
 - » Best fit routines
 - » AutoTune:
 - Transferability of measuring programs between machines of the same type.
 - » MultiCapture:
 - MultiCapture allows all 2D features within a field of view to be captured simultaneously, regardless of the feature type. Inspection speeds can be increased by 35 % or more, depending on the feature size and density. The capture sequence for groups of features using MultiCapture is also automatically optimised, creating the most efficient possible path with the fewest number of stage movements.
 - » RGB Sensitivity Adjustments for colour cameras: Software controls for Red/Green/Blue (RGB) sensitivity in images from a colour camera allow for fine control adjustment over image contrast. This capability improves overall consistency in vision inspection in general and is especially useful for coloured parts where edges can be difficult to capture with grayscale or lighting modifications alone.

Illumination for Vision sensor

- Coaxial LED top light
- Telecentric LED back light
- 12-segment LED ring light (white LEDs)
 - » 3 rings with 3 different angles of incidence (27 °, 35 °, 45 °) and 4 segments each

CNC zoom

- 10x motorised zoom, for a continuous adjustment of field of view and resolution
- High resolution 1/1.8-inch CMOS camera (H 1280 x V 1024 pixels) monochrome (standard) or colour (optional) with Gigabit Ethernet interface

Magnification variants of the 10x CNC zoom (1)							
Lens	Magni- fication	Working distance (mm)	Max. workpiece height (mm)	Max. field of view (mm)	Min. field of view (mm)	Pixel size (µm/pixel)	Screen magnifi- cation (2)
Stan- dard	0.64x to 6.4x	86	0 to 300	10.6 x 8.5	1.06 x 0.85	8.3 to 0.83	43x to 427x

Optiv Dual Camera (optional)

- In two steps electronically switchable magnification by factor 1:3.3
- Camera #1: 1/3-inch CCD camera (monochrome)
 - » H 752 x V 582 pixel
- Camera #2: 2/3-inch CCD camera (monochrome)
 - » H 752 x V 582 pixel
- Available lenses: 3x, 5x, 10x

Magnification variants of the Optiv Dual Camera optics (camera #1, detail mode / camera #2, overview mode) (©)					
Optical magnification of the lens	Working distance (mm)	Pixel size (µm/pixel)	Field of view H x V (mm)	Screen magnification ⁽⁴⁾	
3x	75	2.12 / 7.03	1.6 x 1.2 / 5.3 x 4.1	278x / 84x	
5x	64	1.27 / 4.22	1.0 x 0.7 / 3.2 x 2.5	463x / 138x	
10x	48	0.64 / 2.11	0.5 × 0.4 / 1.6 × 1.2	925x / 281x	

Technical description

- Optical sensor for focussing and scanning purposes according to the principle of chromatic length aberration of white light
- · Surface independent and robust measurement with a resolution in the nanometer range

	10 mm ⁽⁵⁾	3 mm ⁽⁵⁾	600 μm ⁽⁵⁾	300 μm ⁽⁵⁾
Working distance	70 mm	22.5 mm	6.5 mm	4.5 mm
Resolution in Z direction	300 nm	100 nm	20 nm	10 nm
Diameter of the CWS spot	24 µm	12 µm	4 µm	5 µm

Chromatic White Light Sensor (CWS, optional)

(5) Measuring range CWS: see pages 9 and 10

⁽¹⁾ Values rounded

⁽²⁾ On a 22-inch (16:9) monitor, PC-DMIS "Scale to Fit" —> OFF

⁽³⁾ Values rounded

⁽⁴⁾ On a 22-inch (16:9) monitor, PC-DMIS "Scale to Fit" —> OFF

Through-The-Lens laser (TTL laser, optional)

Technical description

- Available only for systems equipped with Optiv Dual Camera
- Available for 5x and 10x lens
- Coaxial reflection into the optical path of the Vision sensor
- Measuring principle: Foucault and triangulation method
- Functionality:
 - » Autofocus sensor for quick focussing of the Vision sensor and measuring heights, bore depths and flatness
 - » Scanning sensor for the contour and surface scanning
- Laser safety class 2, average output < 1 mW
- Red laser, wavelength 650 nm to 680 nm
- Spot size approx. 100 µm at 5x lens and accordingly approx. 50 µm at 10x lens
- Resolution ± 0.1 µm

Optional stylus

rack

module changing

- Measuring accuracy within E1 (at 10x lens)
- Average focus speed 0.2 s
- Scanning feature in conjunction with PC-DMIS CAD++

	TP200 ⁽¹⁾	HP-TM ⁽¹⁾	
Technical description	 6-way touch-trigger probe Using innovative micro strain gauge technology Allows for small trigger forces and offers advanced triggering accuracy as well as long reliable operation 	 5-way touch-trigger probe Sensor body and stylus holding module are magnetically connected to each other Stylus holding modules available in four versions with different trigger forces 	
Measuring accuracy (at 20°C, according to ISO 10360-2)	MPE _P = 2.5 μm	MPE _P = 3.4 μm	
Mounting	M8 thread (probe body), M2 thread (styli)		
Stylus holding LF low force SF standard force		LF low force SF standard force MF medium force EF extended force	
Trigger force	X, Y: 0.02 N / Z: 0.07 N (all modules)	0.055 N (LF module) 0.08 N (SF module) 0.10 N (MF module) 0.10 N (EF module)	

With 3 or 6 slots

Touch-trigger probes TP200, HP-TM (optional)

⁽¹⁾ Mutual measuring range Vision-Sensor <--> Touch-trigger probe in X direction = 495 mm(see pages 9 and 10)

HR-P4 or HR-P6

(with 4 or 6 slots)

TECHNICAL DATA

Scanning probe HP-S-X1C (standard), HP-S-X1S/H (optional)

(1) Mutual measuring range Vision-Sensor <--> HP-S-X1 in X direction = 495 mm(see pages 9 and 10)

		HP-S-X1S (1)	HP-S-X1H (1)	
	HP-S-X1C (1)	HH-A-T5 motorised indexing probe head (optional)		
Technical description	High accuracy 3D scanning probe head that supports single point probing, self-centring as well as continuous high-speed-scanning for fast and accurate form and profile measurements			
Probe head type	Analog			
Stylus joint	M3			
Resolution	< 0.1 μm			
Measuring range	± 2 mm in all axes			
Linear stiffness	1.2 N/mm			
Stylus length range	Vertical: up to 225 mm Horizontal: up to 100 mm	Vertical: up to 115 mm Horizontal: up to 20 mm	Vertical: up to 225 mm Horizontal: up to 100 mm	
Stylus module changing rack	HR-X1 with 3 or 6 slots			

Indexable motorised probe head HH-A-T5 (optional)

Technical description

- · Motorised indexing probe head featuring high speed rotation and high torque
- Equipped with a kinematic joint (TKJ) which is a multiwire connection allowing the support of multiple types of sensors
- Angular rotation step: 5°
- A axis: +90° to -115°, B axis: ±180°
- Total number of positions: 3,024
- Positioning repeatability: 0.5 μm
- Probe mounting: TKJ multiwire

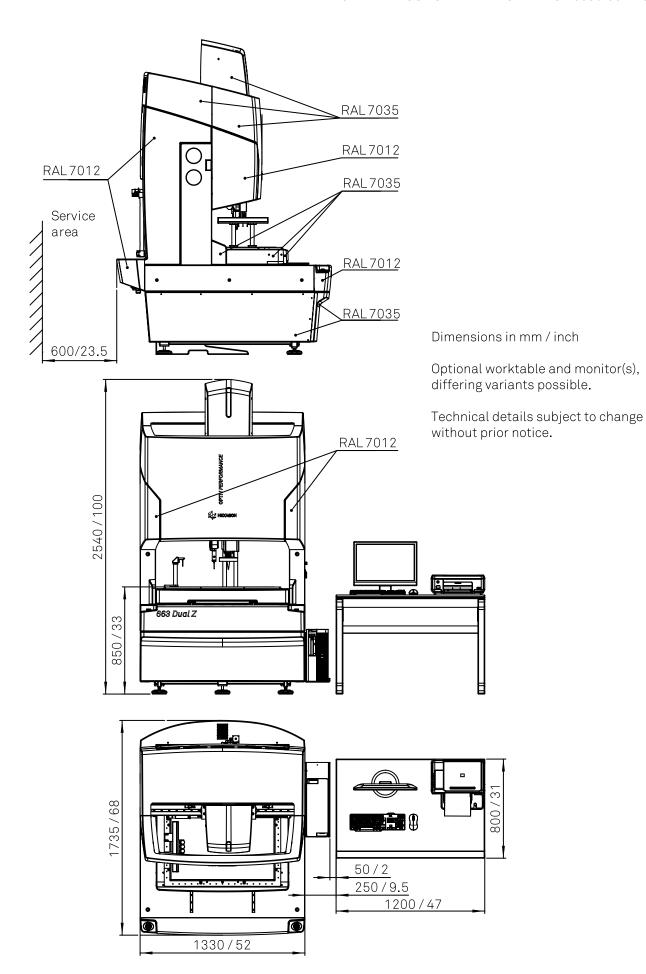
Other optional equipment

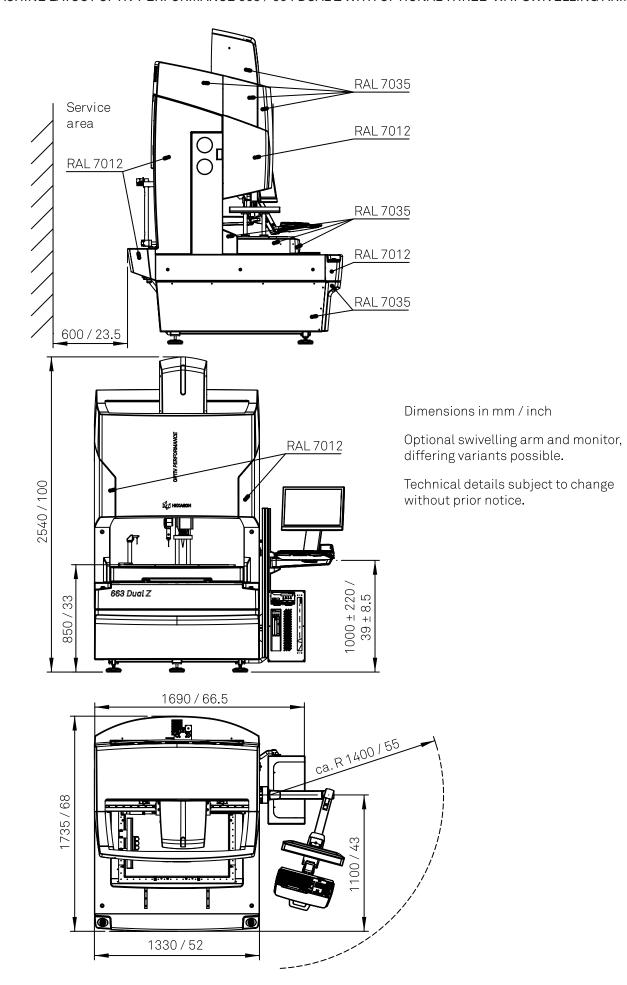
(2) From quarter 3/2016, only for Optiv Performance 664 Dual Z

- · Vibration damping system
- Mechanical bearing CNC rotary table
- Mechanical bearing CNC stacked rotary tables (Optiv Dual Rotary) (2)
- Stylus module changing rack
- Motorised indexing probe heads
- · Periphery:
 - » Worktable, printers, monitors
 - » Uninterruptible power supply (UPS)

Control system and safety regulations

- · Machine control unit
 - » DELL computer system with Microsoft Windows 7 Professional (64 bit)
- CNC controller:
 - » Microprocessor CNC with vector path control
- · Safety equipment:
 - » Emergency-Stop circuit with Emergency-Stop button
 - » Scale signal monitoring
 - » Safety limit switches
 - » Protective covers for the axes' drives
 - » Collision protection for touch-trigger probes
- Safety regulations:
 - » DIN EN ISO 12100-1 and -2 (Safety of machinery)
 - » DIN EN 60204-1 (Safety of machinery Electrical equipment of machines)
 - » DIN EN ISO 13849-1 (Safety of machinery Safety-related parts of control systems)
 - » DIN EN 61000-4-2 and -4 (Electromagnetic compatibility EMC, immunity of machines)
 - » DIN EN 55011 (Industrial, scientific and medical equipment Radio-frequency disturbance characteristics)





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Dimensions in mm / inch

Technical details subject to change without prior notice.

Size of all threads M6 - 12 deep

Offset camera + touch-probe 115 mm / 4.5 inch

Offset camera + CWS 83 mm / 3 inch



Mutual measuring range of all sensors



Measuring range camera



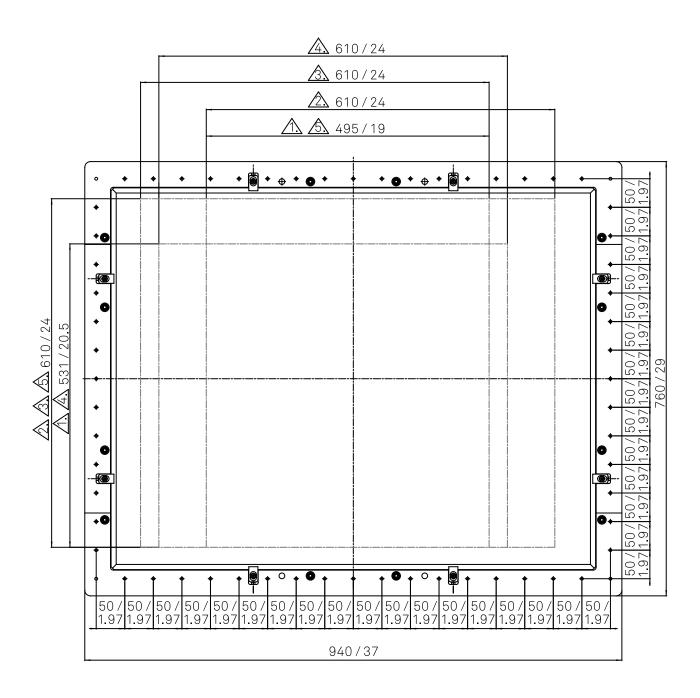
Measuring range touch-probe

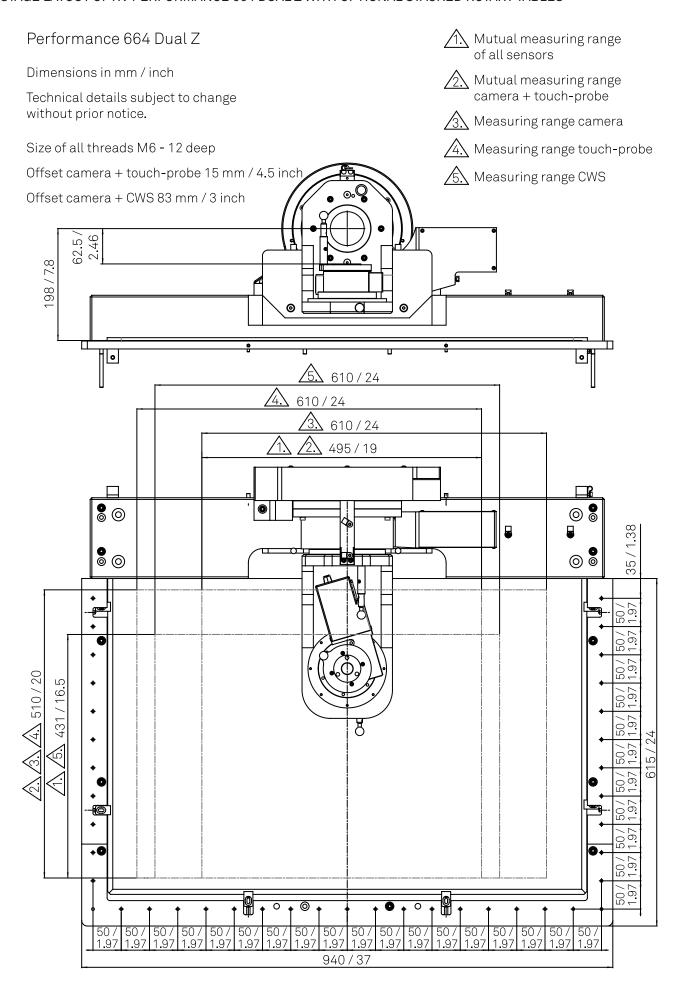


Measuring range CWS



Mutual measuring range camera + touch-probe







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METROLOGY SOFTWARE SOLUTIONS

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